

# ELLIPTIC FUNCTION SOLUTIONS FOR SOME NONLINEAR PDES IN MATHEMATICAL PHYSICS

Yusuf Gurefe<sup>1</sup>, Yusuf Pandir<sup>2,†</sup>, Tolga Akturk<sup>3</sup>  
and Hasan Bulut<sup>3</sup>

**Abstract** In this work, we have constructed various types of soliton solutions of the generalized regularized long wave and generalized nonlinear Klein-Gordon equations by the using of the extended trial equation method. Some of the obtained exact traveling wave solutions to these nonlinear problems are the rational function, 1-soliton, singular, the elliptic integral functions  $F, E, \Pi$  and the Jacobi elliptic function  $\text{sn}$  solutions. Also, all of the solutions are compared with the exact solutions in literature, and it is seen that some of the solutions computed in this paper are new wave solutions.

**Keywords** Extended trial equation method, generalized regularized long wave, generalized Klein-Gordon equation, soliton solutions, elliptic solutions.

**MSC(2010)** 35C07, 35C08, 37K40.

## 1. Introduction

The nonlinear physical phenomena have very importance in various fields of physics and applied mathematics. Recently, a lot of methods have been defined for getting new wave solutions to nonlinear partial differential equations that model to express these phenomena. Some of them are Hirota method, Exp-function method,  $(G/G)$ -expansion method, ansatz method, mapping method, Kudryashovs method, multiple and double exp-function methods, three wave method, superposition method, sine-cosine method, asymptotic method [1, 3, 5, 8, 10, 13–15, 19–21, 25–31]. Moreover, the trial equation method is proposed to solve nonlinear wave equations by Liu [16–18]. After this method, Du has defined a new version of the trial equation method called as irrational trial equation method. Also, the trial equation method is modified by Gurefe et al. [12] and given two important applications of this method. Then, the extended trial method, which is a more general form of the trial equation methods, is constructed by Pandir et al. [4, 11, 22–24]. The elliptic integral functions and Jacobi elliptic functions solutions are determined by the applying of this method to some nonlinear partial differential equations. These new solutions appear in various fields of physics. In Section 2, we explain the extended trial equation method as detail. In Section 3, as applications, we obtain some exact

---

<sup>†</sup>the corresponding author. Email address: [yusufpandir@gmail.com](mailto:yusufpandir@gmail.com) (Y. Pandir)

<sup>1</sup>Department of Econometrics, Faculty of Economics and Administrative Sciences, Usak University, 64200 Usak, Turkey

<sup>2</sup>Department of Mathematics, Faculty of Science and Arts, Bozok University, 66100 Yozgat, Turkey

<sup>3</sup>Department of Mathematics, Faculty of Science, Firat University, 23100 Elazig, Turkey

solutions to the generalized regularized long wave given by [2,9]

$$u_t + u_x + \delta u^q u_x - \gamma u_{xxt} = 0, \quad q \in \mathbb{Z}^+, \tag{1.1}$$

where  $\delta$  and  $\gamma$  are positive constants that describe the behavior of the undular bore, and generalized nonlinear Klein-Gordon equation [7]

$$u_{tt} - a^2 u_{xx} + \alpha u - \beta u^\gamma = 0, \quad \gamma \in \mathbb{Z}^+, \tag{1.2}$$

where  $a$  is positive constant and  $\alpha, \beta \neq 0$ .

## 2. The extended trial equation method

*Step 1.* For a given nonlinear partial differential equation

$$P(u, u_t, u_x, u_{xx}, \dots) = 0, \tag{2.1}$$

take the wave transformation

$$u(x_1, x_2, \dots, x_N, t) = u(\eta), \quad \eta = \lambda \left( \sum_{j=1}^N x_j - ct \right), \tag{2.2}$$

where  $\lambda \neq 0$  and  $c \neq 0$ . Substituting Eq. (2.2) into Eq. (2.1) yields a nonlinear ordinary differential equation,

$$N(u, u', u'', \dots) = 0. \tag{2.3}$$

*Step 2.* Take transformation and trial equation as follows:

$$u = \sum_{i=0}^{\delta} \tau_i \Gamma^i, \tag{2.4}$$

where

$$(\Gamma')^2 = \Lambda(\Gamma) = \frac{\Phi(\Gamma)}{\Psi(\Gamma)} = \frac{\xi_\theta \Gamma^\theta + \dots + \xi_1 \Gamma + \xi_0}{\zeta_\epsilon \Gamma^\epsilon + \dots + \zeta_1 \Gamma + \zeta_0}. \tag{2.5}$$

Using the relations 2.4 and 2.5, we can find

$$(u')^2 = \frac{\Phi(\Gamma)}{\Psi(\Gamma)} \left( \sum_{i=0}^{\delta} i \tau_i \Gamma^{i-1} \right)^2, \tag{2.6}$$

$$u'' = \frac{\Phi'(\Gamma)\Psi(\Gamma) - \Phi(\Gamma)\Psi'(\Gamma)}{2\Psi^2(\Gamma)} \left( \sum_{i=0}^{\delta} i \tau_i \Gamma^{i-1} \right) + \frac{\Phi(\Gamma)}{\Psi(\Gamma)} \left( \sum_{i=0}^{\delta} i(i-1) \tau_i \Gamma^{i-2} \right), \tag{2.7}$$

where  $\Phi(\Gamma)$  and  $\Psi(\Gamma)$  are polynomials. Substituting these terms into Eq. (2.3) yields an equation of polynomial  $\Omega(\Gamma)$  of  $\Gamma$  :

$$\Omega(\Gamma) = \varrho_s \Gamma^s + \dots + \varrho_1 \Gamma + \varrho_0 = 0. \tag{2.8}$$

According to the balance principle we can determine a relation of  $\theta, \epsilon,$  and  $\delta$ . We can take some values of  $\theta, \epsilon,$  and  $\delta$ .

*Step 3.* Let the coefficients of  $\Omega(\Gamma)$  all be zero will yield an algebraic equations system:

$$\varrho_i = 0, \quad i = 0, \dots, s. \quad (2.9)$$

Solving this equations system (2.9), we will determine the values of  $\xi_0, \dots, \xi_\theta; \zeta_0, \dots, \zeta_\epsilon$  and  $\tau_0, \dots, \tau_\delta$ .

*Step 4.* Reduce Eq. (2.5) to the elementary integral form,

$$\pm(\eta - \eta_0) = \int \frac{d\Gamma}{\sqrt{\Lambda(\Gamma)}} = \int \sqrt{\frac{\Psi(\Gamma)}{\Phi(\Gamma)}} d\Gamma. \quad (2.10)$$

Using a complete discrimination system for polynomial to classify the roots of  $\Phi(\Gamma)$ , we solve the infinite integral (2.10) and with the help of MATHEMATICA and classify the exact approximate solutions to Eq (2.1) respectively.

### 3. Application to the extended trial equation method

In this section, we apply the method developed in Section 2 to the generalized regularized long wave (GRLW) and the generalized nonlinear Klein-Gordon equation, respectively.

#### 3.1. Application to the GRLW equation

In order to look for travelling wave solutions of eq. (1.1), we make the transformation  $u(x, t) = u(\eta), \eta = kx + wt$ , where  $w$  is an arbitrary constant. Then, integrating the resulting equation with respect to  $\eta$  and setting the integration constant to zero, we obtain

$$wu + ku + \frac{\delta k}{q+1}u^{q+1} - \gamma wk^2 u'' = 0. \quad (3.1)$$

Using the transformation

$$u = v^{\frac{1}{q}}, \quad (3.2)$$

Eq. (3.1) turns into the equation

$$q^2(q+1)(w+k)v^2 + \delta kq^2v^3 - \gamma wk^2(1-q)(1+q)(v')^2 - \gamma wk^2q(q+1)vv'' = 0. \quad (3.3)$$

Substituting Eqs. (2.6) and (2.7) into Eq. (3.3), and using the balance principle, we find

$$\theta = \epsilon + \delta + 2.$$

After this solution procedure, we obtain the results as follows:

Case 1: If we take  $\epsilon = 0, \delta = 1$  and  $\theta = 3$ , then

$$(v')^2 = \frac{\tau_1^2(\xi_3\Gamma^3 + \xi_2\Gamma^2 + \xi_1\Gamma + \xi_0)}{\zeta_0}, \quad (3.4)$$

$$v'' = \frac{\tau_1(3\xi_3\Gamma^2 + 2\xi_2\Gamma + \xi_1)}{2\zeta_0}, \quad (3.5)$$

where  $\xi_3 \neq 0, \zeta_0 \neq 0$ . Respectively, solving the algebraic equation system (2.9) yields

$$\xi_0 = \xi_0, \xi_1 = \xi_1, \xi_2 = \frac{\xi_1^2 q(q-4)}{4\xi_0(q-1)^2}, \xi_3 = -\frac{\xi_1^3 q^2}{4\xi_0^2(q-1)^3}, \tau_0 = \tau_0, \tag{3.6}$$

$$\tau_1 = \frac{q\xi_1\tau_0}{2\xi_0(q-1)}, \zeta_0 = \frac{k^2(q+2)\gamma\xi_1^2(1+q+\delta\tau_0)}{4q\delta\xi_0\tau_0(q-1)^2}, w = -\frac{k(1+q+\delta\tau_0)}{q+1}. \tag{3.7}$$

Substituting these results into Eqs. (2.5) and (2.10), we get

$$\pm(\eta - \eta_0) = \sqrt{A} \int \frac{d\Gamma}{\sqrt{\Gamma^3 - \frac{\xi_0(q-1)(q-4)}{\xi_1 q} \Gamma^2 - \frac{4\xi_0^2(q-1)^3}{\xi_1^2 q^2} \Gamma - \frac{4\xi_0^3(q-1)^3}{\xi_1^3 q^2}}}, \tag{3.8}$$

where  $A = -\frac{k^2(q-1)(q+2)\gamma\xi_0(1+q+\delta\tau_0)}{\delta q^3 \xi_1 \tau_0}$ . Integrating eq. (3.8), we obtain the solutions to the eq. (1.1) as follows:

$$\pm(\eta - \eta_0) = -2\sqrt{A} \frac{1}{\sqrt{\Gamma - \alpha_1}}, \tag{3.9}$$

$$\pm(\eta - \eta_0) = 2\sqrt{\frac{A}{\alpha_2 - \alpha_1}} \arctan \sqrt{\frac{\Gamma - \alpha_2}{\alpha_2 - \alpha_1}}, \quad \alpha_2 > \alpha_1, \tag{3.10}$$

$$\pm(\eta - \eta_0) = \sqrt{\frac{A}{\alpha_1 - \alpha_2}} \ln \left| \frac{\sqrt{\Gamma - \alpha_2} - \sqrt{\alpha_1 - \alpha_2}}{\sqrt{\Gamma - \alpha_2} + \sqrt{\alpha_1 - \alpha_2}} \right|, \quad \alpha_1 > \alpha_2, \tag{3.11}$$

$$\pm(\eta - \eta_0) = 2\sqrt{\frac{A}{\alpha_1 - \alpha_3}} F(\varphi_1, l_1), \quad \alpha_1 > \alpha_2 > \alpha_3, \tag{3.12}$$

where

$$F(\varphi_1, l_1) = \int_0^{\varphi_1} \frac{d\psi}{\sqrt{1 - l_1^2 \sin^2 \psi}}, \tag{3.13}$$

and

$$\varphi_1 = \arcsin \sqrt{\frac{\Gamma - \alpha_3}{\alpha_2 - \alpha_3}}, \quad l_1^2 = \frac{\alpha_2 - \alpha_3}{\alpha_1 - \alpha_3}. \tag{3.14}$$

Also  $\alpha_1, \alpha_2$  and  $\alpha_3$  are the roots of the polynomial equation

$$\Gamma^3 + \frac{\xi_2}{\xi_3} \Gamma^2 + \frac{\xi_1}{\xi_3} \Gamma + \frac{\xi_0}{\xi_3} = 0. \tag{3.15}$$

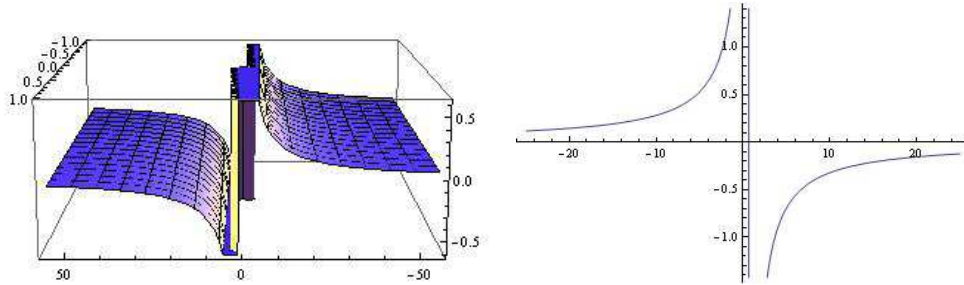
Substituting the solutions (3.9-3.12) into (2.4) and (3.2), we can find the following exact traveling wave solutions such as rational function solution, hyperbolic function solutions and Jacobi elliptic function solutions to Eq. (1.1), respectively:

$$u(x, t) = \left[ \tau_0 + \tau_1 \alpha_1 + \frac{4\tau_1 A}{\left( kx - \frac{k(1+q+\delta\tau_0)}{q+1} t - \eta_0 \right)^2} \right]^{\frac{1}{q}}, \tag{3.16}$$

$$u(x, t) = \left( \tau_0 + \tau_1 \alpha_1 + \tau_1 (\alpha_2 - \alpha_1) \tanh^2 \left[ B \left( x - \frac{1+q+\delta\tau_0}{q+1} t - \frac{\eta_0}{k} \right) \right] \right)^{\frac{1}{q}}, \tag{3.17}$$

$$u(x, t) = \left( \tau_0 + \tau_1 \alpha_1 + \tau_1 (\alpha_1 - \alpha_2) \operatorname{cosech}^2 \left[ B \left( x - \frac{1+q+\delta\tau_0}{q+1} t - \frac{\eta_0}{k} \right) \right] \right)^{\frac{1}{q}}, \tag{3.18}$$

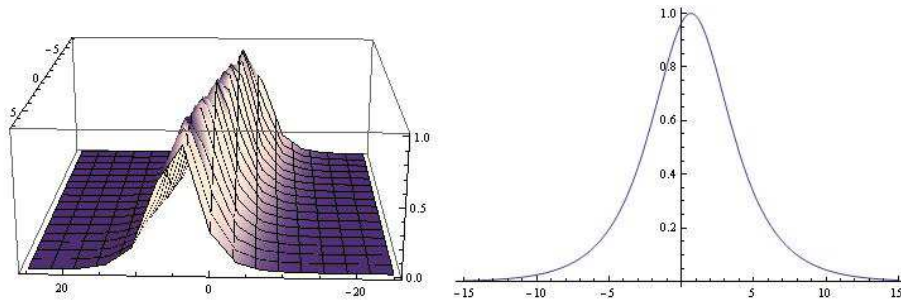
and



**Figure 1.** The solution (3.20) is shown at  $\tau_0 = \tau_1 = \alpha_1 = \xi_0 = \xi_1 = \delta = \gamma = k = 1$ ,  $\eta_0 = 0$ ,  $q = 2$  and the second graph represents the exact approximate solution of Eq. (3.20) for  $t = 1$ .

$$u(x, t) = \left( \tau_0 + \tau_1 \alpha_3 + \tau_1 (\alpha_2 - \alpha_3) \operatorname{sn}^2 \left[ B_i \left( kx - \frac{k(1 + q + \delta \tau_0)}{q + 1} t - \frac{\eta_0}{k} \right), l_1^2 \right] \right)^{\frac{1}{q}}, \tag{3.19}$$

where  $B = \frac{k}{2} \sqrt{\frac{\alpha_1 - \alpha_2}{A}}$  and  $B_i = \frac{(-1)^i k}{2} \sqrt{\frac{\alpha_1 - \alpha_3}{A}}$ , ( $i = 1, 2$ ). If we take  $\tau_0 = -\tau_1 \alpha_1$



**Figure 2.** The solution (3.21) is shown at  $\tau_0 = \tau_1 = \alpha_1 = \xi_0 = \xi_1 = \delta = \gamma = k = 1$ ,  $\eta_0 = 0$ ,  $\alpha_2 = q = 2$  and the second graph represents the exact approximate solution of Eq. (3.21) for  $t = 1$ .

and  $\eta_0 = 0$  for simplicity, then the solutions (3.16)-(3.18) can reduce to rational function solution

$$u(x, t) = \left( \frac{2\sqrt{\tilde{A}}}{k(x - vt)} \right)^{\frac{2}{q}}, \tag{3.20}$$

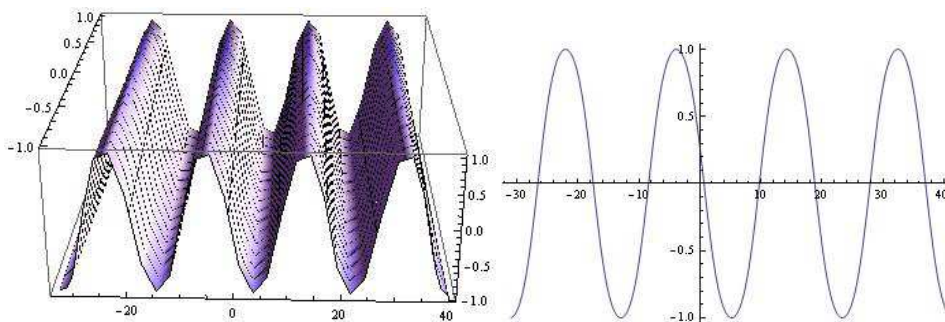
1-soliton solution

$$u(x, t) = \frac{A_1}{\cosh^{\frac{2}{q}} [B(x - vt)]}, \tag{3.21}$$

singular soliton solution

$$u(x, t) = \frac{A_2}{\sinh^{\frac{2}{q}} [B(x - vt)]}, \tag{3.22}$$

where  $\tilde{A} = \tau_1 A$ ,  $A_1 = (\tau_1 (\alpha_2 - \alpha_1))^{\frac{1}{q}}$ ,  $A_2 = (\tau_1 (\alpha_1 - \alpha_2))^{\frac{1}{q}}$  and  $v = \frac{1+q-\delta\tau_1\alpha_1}{q+1}$ . Here,  $A_1$  and  $A_2$  are the amplitudes of the solitons, while  $v$  is the velocity and  $B$  is the inverse width of the solitons. Thus, we can say that the solitons exist for



**Figure 3.** The solution (3.23) is shown at  $\tau_0 = \tau_1 = \alpha_1 = \xi_0 = \xi_1 = \delta = \gamma = k = 1$ ,  $\eta_0 = 0$ ,  $\alpha_3 = q = 2$ ,  $\alpha_1 = 3$  and the second graph represents the exact approximate solution of Eq. (3.23) for  $t = 1$ .

$\tau_1 > 0$ . On the other hand, if we take  $\tau_0 = -\tau_1\alpha_3$  and  $\eta_0 = 0$ , the Jacobi elliptic function solution (3.19) can be written in the form

$$u_i(x, t) = A_3 \operatorname{sn}^{\frac{2}{q}} \left[ B_i(x - vt), \frac{\alpha_2 - \alpha_3}{\alpha_1 - \alpha_3} \right], \tag{3.23}$$

where  $A_3 = (\tau_1(\alpha_2 - \alpha_3))^{\frac{1}{q}}$  and  $B_i = \frac{(-1)^i k}{2} \sqrt{\frac{\alpha_1 - \alpha_3}{A}}$ , ( $i = 1, 2$ ).

**Remark 3.1.** Substituting the exact solutions (3.20)-(3.23), that the extended trial equation method gives us, into Eq. (1.1), it is seen that these solutions provide Eq. (1.1). Also, rational function and Jacobi elliptic function solutions are not found in the previous literature.

**Remark 3.2.** When the modulus  $l_1 \rightarrow 1$ , the solution (3.23) can be converted into dark soliton solutions of the generalized regularized long wave equation

$$u_i(x, t) = A_3 \tanh^{\frac{2}{q}} [B_i(x - vt)], \quad (i = 1, 2), \tag{3.24}$$

where  $\alpha_1 = \alpha_2$ , and  $v$  represents the velocity of the dark soliton.

Case 2

If we take  $\epsilon = 0$ ,  $\delta = 2$  and  $\theta = 4$ , then

$$(v')^2 = \frac{(\tau_1 + 2\tau_2\Gamma)^2(\xi_4\Gamma^4 + \xi_3\Gamma^3 + \xi_2\Gamma^2 + \xi_1\Gamma + \xi_0)}{\zeta_0}, \tag{3.25}$$

$$v'' = \frac{(\tau_1 + 2\tau_1\Gamma)(4\xi_4\Gamma^3 + 3\xi_3\Gamma^2 + 2\xi_2\Gamma + \xi_1)}{2\zeta_0} \tag{3.26}$$

$$+ \frac{2\tau_2(\xi_4\Gamma^4 + \xi_3\Gamma^3 + \xi_2\Gamma^2 + \xi_1\Gamma + \xi_0)}{\zeta_0}, \tag{3.27}$$

where  $\xi_4 \neq 0$ ,  $\zeta_0 \neq 0$ . Respectively, solving the algebraic equation system (2.9)

yields as follows:

$$\begin{aligned}\xi_0 &= \frac{q^2 \delta \zeta_0 \tau_1^4 + 4k^2 \gamma \xi_1 \tau_1 \tau_2 (\delta \tau_1^2 + 2\tau_2(q+1)(q+2))}{32k^2 \gamma \tau_2^2 (\delta \tau_1^2 + \tau_2(q+1)(q+2))}, \quad \xi_1 = \xi_1, \quad \tau_0 = \frac{\tau_1^2}{4\tau_2}, \\ \xi_2 &= \frac{2k^2 \gamma \xi_1 \tau_1 \tau_2 (3\delta \tau_1^2 + \tau_2(q+1)(q+2)) - q^2 \delta \zeta_0 \tau_1^3}{2k^2 \gamma \tau_1 (\delta \tau_1^2 + \tau_2(q+1)(q+2))}, \quad \tau_1 = \tau_1, \quad \tau_2 = \tau_2, \\ \xi_3 &= \frac{\delta \tau_2 (4k^2 \delta \xi_1 \tau_2 - q^2 \zeta_0 \tau_1)}{k^2 \gamma (\delta \tau_1^2 + \tau_2(q+1)(q+2))}, \quad \xi_4 = \frac{\delta \tau_2^2 (4k^2 \delta \xi_1 \tau_2 - q^2 \zeta_0 \tau_1)}{2k^2 \gamma \tau_1 (\delta \tau_1^2 + \tau_2(q+1)(q+2))}, \\ \zeta_0 &= \zeta_0, \quad w = -\frac{kq^2 \zeta_0 \tau_1 (\delta \tau_1^2 + \tau_2(q+1)(q+2))}{\tau_2(q+1)(q+2) (q^2 \zeta_0 \tau_1 - 4k^2 \delta \xi_1 \tau_2)}.\end{aligned}\quad (3.28)$$

Substituting these results into Eqs. (2.5) and (2.10), we get

$$\pm (\eta - \eta_0) = C \int \frac{d\Gamma}{\sqrt{\Gamma^4 + \frac{\xi_3}{\xi_4} \Gamma^3 + \frac{\xi_2}{\xi_4} \Gamma^2 + \frac{\xi_1}{\xi_4} \Gamma + \frac{\xi_0}{\xi_4}}}, \quad (3.29)$$

where  $C = \sqrt{\frac{2k^2 \gamma \tau_1 \zeta_0 (\delta \tau_1^2 + \tau_2(q+1)(q+2))}{\delta \tau_2^2 (4k^2 \delta \xi_1 \tau_2 - q^2 \zeta_0 \tau_1)}}$ . Integrating Eq. (3.29), we obtain the solutions to the eq. (1.1) as follows:

$$\pm (\eta - \eta_0) = -\frac{C}{\Gamma - \alpha_1}, \quad (3.30)$$

$$\pm (\eta - \eta_0) = \frac{2C}{\alpha_1 - \alpha_2} \sqrt{\frac{\Gamma - \alpha_2}{\Gamma - \alpha_1}}, \quad \alpha_1 > \alpha_2, \quad (3.31)$$

$$\pm (\eta - \eta_0) = \frac{C}{\alpha_1 - \alpha_2} \ln \left| \frac{\Gamma - \alpha_1}{\Gamma - \alpha_2} \right|, \quad (3.32)$$

$$\pm (\eta - \eta_0) = \frac{2C}{\sqrt{(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)}} \ln \left| \frac{Y_1(\Gamma) - G_1(\Gamma)}{Y_1(\Gamma) - G_1(\Gamma)} \right|, \quad \alpha_1 > \alpha_2 > \alpha_3, \quad (3.33)$$

$$\pm (\eta - \eta_0) = \frac{2C}{\sqrt{(\alpha_1 - \alpha_3)(\alpha_2 - \alpha_4)}} F(\varphi_2, l_2), \quad \alpha_1 > \alpha_2 > \alpha_3 > \alpha_4, \quad (3.34)$$

where

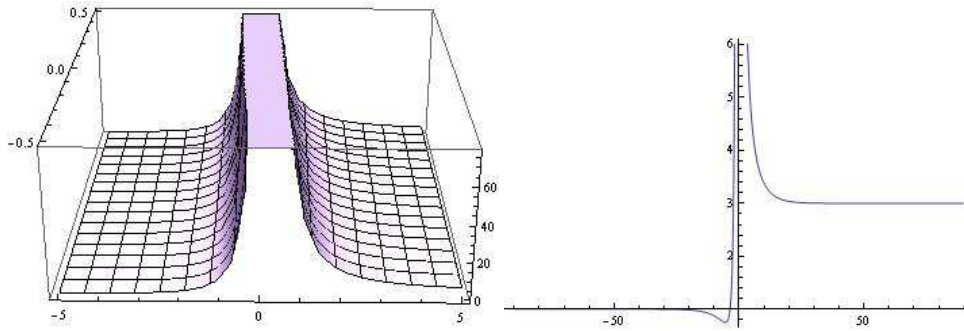
$$Y_1(\Gamma) = \sqrt{(\Gamma - \alpha_2)(\alpha_1 - \alpha_3)}, \quad G_1(\Gamma) = \sqrt{(\Gamma - \alpha_3)(\alpha_1 - \alpha_2)}$$

and

$$\varphi_2 = \arcsin \sqrt{\frac{(\Gamma - \alpha_1)(\alpha_2 - \alpha_4)}{(\Gamma - \alpha_2)(\alpha_1 - \alpha_4)}}, \quad l_2^2 = \frac{(\alpha_2 - \alpha_3)(\alpha_1 - \alpha_4)}{(\alpha_1 - \alpha_3)(\alpha_2 - \alpha_4)}. \quad (3.35)$$

Also  $\alpha_1, \alpha_2, \alpha_3$  and  $\alpha_4$  are the roots of the polynomial equation

$$\Gamma^4 + \frac{\xi_3}{\xi_4} \Gamma^3 + \frac{\xi_2}{\xi_4} \Gamma^2 + \frac{\xi_1}{\xi_4} \Gamma + \frac{\xi_0}{\xi_4} = 0. \quad (3.36)$$



**Figure 4.** The solution (3.45) is shown at  $\tau_0 = \tau_2 = \alpha_1 = \xi_0 = \zeta_0 = \delta = \gamma = q = k = 1$ ,  $\eta_0 = 0$ ,  $\xi_1 = \tau_1 = -1$ ,  $\alpha_2 = 2$  and the second graph represents the exact approximate solution of Eq. (3.45) for  $t = 1$ .

Substituting the solutions (3.30)-(3.34) into (2.4) and (3.2), we have

$$u(x, t) = \left[ \tau_0 + \tau_1 \alpha_1 \pm \frac{\tau_1 C}{kx + wt - \eta_0} + \tau_2 \left( \alpha_1 \pm \frac{C}{kx + wt - \eta_0} \right)^2 \right]^{\frac{1}{q}}, \quad (3.37)$$

$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_1 + \frac{4C^2(\alpha_2 - \alpha_1)\tau_1}{4C^2 - [(\alpha_1 - \alpha_2)(kx + wt - \eta_0)]^2} + \tau_2 \left( \alpha_1 + \frac{4C^2(\alpha_2 - \alpha_1)}{4C^2 - [(\alpha_1 - \alpha_2)(kx + wt - \eta_0)]^2} \right)^2 \right\}^{\frac{1}{q}}, \quad (3.38)$$

$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_2 + \frac{(\alpha_2 - \alpha_1)\tau_1}{\exp [B_3 (x - vt - \frac{\eta_0}{k})] - 1} + \tau_2 \left( \alpha_2 + \frac{\alpha_2 - \alpha_1}{\exp [B_3 (x - vt - \frac{\eta_0}{k})] - 1} \right)^2 \right\}^{\frac{1}{q}}, \quad (3.39)$$

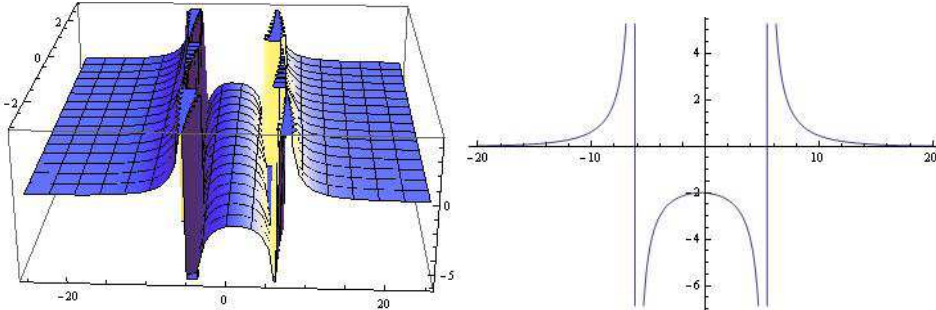
$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_1 + \frac{(\alpha_1 - \alpha_2)\tau_1}{\exp [B_3 (x - vt - \frac{\eta_0}{k})] - 1} + \tau_2 \left( \alpha_1 + \frac{\alpha_1 - \alpha_2}{\exp [B_3 (x - vt - \frac{\eta_0}{k})] - 1} \right)^2 \right\}^{\frac{1}{q}}, \quad (3.40)$$

$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_1 - \frac{2(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)\tau_1}{2\alpha_1 - \alpha_2 - \alpha_3 + (\alpha_3 - \alpha_2) \cosh [D (x - vt - \frac{\eta_0}{k})]} + \tau_2 \left( \alpha_1 - \frac{2(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)}{2\alpha_1 - \alpha_2 - \alpha_3 + (\alpha_3 - \alpha_2) \cosh [D (x - vt - \frac{\eta_0}{k})]} \right)^2 \right\}^{\frac{1}{q}}, \quad (3.41)$$

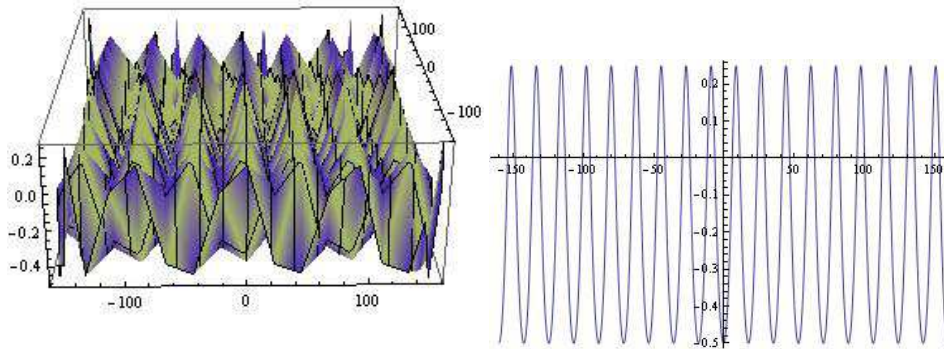
$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_2 + \frac{\tau_1(\alpha_1 - \alpha_2)(\alpha_4 - \alpha_2)}{\alpha_4 - \alpha_2 + (\alpha_1 - \alpha_4) \operatorname{sn}^2 [E (x - vt - \frac{\eta_0}{k}), l_2^2]} + \tau_2 \left( \alpha_2 + \frac{\tau_1(\alpha_1 - \alpha_2)(\alpha_4 - \alpha_2)}{\alpha_4 - \alpha_2 + (\alpha_1 - \alpha_4) \operatorname{sn}^2 [E (x - vt - \frac{\eta_0}{k}), l_2^2]} \right)^2 \right\}^{\frac{1}{q}}, \quad (3.42)$$



where  $B_3 = \frac{k(\alpha_1 - \alpha_2)}{C}$ ,  $D = \frac{k\sqrt{(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)}}{C}$ ,  $E = \frac{k\sqrt{(\alpha_1 - \alpha_3)(\alpha_2 - \alpha_4)}}{2C}$  and  $v =$



**Figure 5.** The solution (3.46) is shown at  $\tau_0 = \tau_2 = \alpha_1 = \xi_0 = \zeta_0 = \delta = \gamma = q = k = 1$ ,  $\eta_0 = 0$ ,  $\xi_1 = \tau_1 = -1$ ,  $\alpha_2 = 2$ ,  $\alpha_3 = 3$  and the second graph represents the exact approximate solution of Eq. (3.46) for  $t = 1$ .



**Figure 6.** The solution (3.47) is shown at  $\tau_2 = \alpha_1 = \xi_0 = \zeta_0 = \delta = \gamma = q = k = 1$ ,  $\eta_0 = 0$ ,  $\xi_1 = \tau_1 = -1$ ,  $\tau_0 = \alpha_2 = \frac{1}{2}$ ,  $\alpha_3 = 3$ ,  $\alpha_4 = 2$  and the second graph represents the exact approximate solution of Eq. (3.47) for  $t = 1$ .

$\frac{q^2 \zeta_0 \tau_1 (\delta \tau_1^2 + \tau_2 (q+1)(q+2))}{\tau_2 (q+1)(q+2)(q^2 \zeta_0 \tau_1 - 4k^2 \delta \xi_1 \tau_2)}$ . For simplicity, if we take  $\eta_0 = 0$ , then we can write the solutions (3.37)-(3.42) as follows:

$$u(x, t) = \left[ \sum_{i=0}^2 \tau_i \left( \alpha_1 \pm \frac{C}{k(x - vt)} \right)^i \right]^{\frac{1}{q}}, \tag{3.43}$$

$$u(x, t) = \left[ \sum_{i=0}^2 \tau_i \left( \alpha_1 + \frac{4C^2(\alpha_1 - \alpha_2)}{4C^2 - [(\alpha_1 - \alpha_2)k(x - vt)]^2} \right)^i \right]^{\frac{1}{q}}, \tag{3.44}$$

$$u(x, t) = \left[ \sum_{i=0}^2 \tau_i \left( \alpha_2 + \frac{\alpha_2 - \alpha_1}{\exp[B_3(x - vt)] - 1} \right)^i \right]^{\frac{1}{q}}, \tag{3.45}$$

$$u(x, t) = \left[ \sum_{i=0}^2 \tau_i \left( \alpha_1 + \frac{\alpha_1 - \alpha_2}{\exp[B_3(x - vt)] - 1} \right)^i \right]^{\frac{1}{q}}, \tag{3.46}$$

$$u(x, t) = \left[ \sum_{i=0}^2 \tau_i \left( \alpha_1 - \frac{2(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)}{2\alpha_1 - \alpha_2 - \alpha_3 + (\alpha_3 - \alpha_2) \cosh [D(x - vt)]} \right) \right]^{\frac{1}{q}}, \quad (3.47)$$

$$u(x, t) = \left[ \sum_{i=0}^2 \tau_i \left( \alpha_2 + \frac{(\alpha_1 - \alpha_2)(\alpha_4 - \alpha_2)}{\alpha_4 - \alpha_2 + (\alpha_1 - \alpha_4) \operatorname{sn}^2 [E(x - vt), l_2]} \right) \right]^{\frac{1}{q}}. \quad (3.48)$$

Here,  $C$  is the amplitude of the soliton, while  $v$  is the velocity and  $D$  and  $E$  are the inverse width of the solitons.

**Remark 3.3.** To our knowledge, the traveling wave solutions (3.43)-(3.48), that we find in this paper, are not shown in the previous literature. These are new exact solutions of Eq. (1.1).

### 3.2. Application to the generalized nonlinear Klein-Gordon equation

In order to look for traveling wave solutions of Eq. (1.2), we make the transformation  $u(x, t) = u(\eta), \eta = k(x - ct)$ , where  $k$  and  $c$  are an arbitrary constant. Consequently, Eq. (1.2) is reduced to the ODE

$$k^2(c^2 - a^2)u''(\eta) + \alpha u - \beta u^\gamma = 0. \quad (3.49)$$

Making use of the transformation:

$$u = v^{\frac{2}{\gamma-1}}, \quad (3.50)$$

Eq. (3.49) converts to the nonlinear ODE:

$$2k^2(c^2 - a^2)(\gamma - 1)vv'' + 2k^2(c^2 - a^2)(3 - \gamma)(v')^2 + \alpha(\gamma - 1)^2v^2 - \beta(\gamma - 1)^2v^4 = 0. \quad (3.51)$$

Substituting Eqs. (2.6) and (2.7) into Eq. (3.51), and using balance principle, we obtain

$$\theta = \epsilon + 2\delta + 2.$$

After this solution procedure, we obtain the results as follows:

Case 1:

If we take  $\epsilon = 0, \delta = 1$  and  $\theta = 4$ , then

$$(v')^2 = \frac{\tau_1^2(\xi_4\Gamma^4 + \xi_3\Gamma^3 + \xi_2\Gamma^2 + \xi_1\Gamma + \xi_0)}{\zeta_0}, \quad (3.52)$$

$$v'' = \frac{\tau_1(4\xi_4\Gamma^3 + 3\xi_3\Gamma^2 + 2\xi_2\Gamma + \xi_1)}{2\zeta_0}, \quad (3.53)$$

where  $\xi_4 \neq 0, \zeta_0 \neq 0$ . Respectively, solving the algebraic equation system (2.9) yields

$$\xi_0 = -\frac{\xi_4\tau_0^2(\alpha + \gamma\alpha - 2\beta\tau_0^2)}{2\beta\tau_1^2}, \quad \xi_1 = \frac{\xi_4\tau_0(4\beta\tau_0^2 - \alpha(\gamma + 1))}{\beta\tau_1^3}, \quad \xi_3 = \frac{4\xi_4\tau_0}{\tau_1}, \quad (3.54)$$

$$\xi_2 = -\frac{\xi_4(\alpha + \gamma\alpha - 12\beta\tau_0^2)}{2\beta\tau_1^2}, \quad c = \pm \sqrt{\frac{2a^2k^2(\gamma + 1)\xi_4 + \beta(\gamma - 1)^2\zeta_0\tau_1^2}{2k^2(\gamma + 1)\xi_4}}, \quad (3.55)$$

where  $\xi_4$ ,  $\zeta_0$ ,  $\tau_0$  and  $\tau_1$  are free parameters. Substituting these results into Eqs. (2.5) and (2.10), we can write

$$\pm(\eta - \eta_0) = H \int \frac{d\Gamma}{\sqrt{\Gamma^4 + \frac{\xi_3}{\xi_4}\Gamma^3 + \frac{\xi_2}{\xi_4}\Gamma^2 + \frac{\xi_1}{\xi_4}\Gamma + \frac{\xi_0}{\xi_4}}}, \quad (3.56)$$

where  $H = \sqrt{\frac{\zeta_0}{\xi_4}}$ ,  $\frac{\xi_3}{\xi_4} = \frac{4\tau_0}{\tau_1}$ ,  $\frac{\xi_2}{\xi_4} = -\frac{\alpha + \gamma\alpha - 12\beta\tau_0^2}{2\beta\tau_1^2}$ ,  $\frac{\xi_1}{\xi_4} = \frac{\tau_0(4\beta\tau_0^2 - \alpha(\gamma + 1))}{\beta\tau_1^3}$ ,  $\frac{\xi_0}{\xi_4} = -\frac{\tau_0^2(\alpha + \gamma\alpha - 2\beta\tau_0^2)}{2\beta\tau_1^2}$ . Integrating Eq. (3.56), we obtain the solutions to the Eq. (1.2) as follows:

$$\pm(\eta - \eta_0) = -\frac{H}{\Gamma - \alpha_1}, \quad (3.57)$$

$$\pm(\eta - \eta_0) = \frac{2H}{\alpha_1 - \alpha_2} \sqrt{\frac{\Gamma - \alpha_2}{\Gamma - \alpha_1}}, \quad \alpha_2 > \alpha_1, \quad (3.58)$$

$$\pm(\eta - \eta_0) = \frac{H}{\alpha_1 - \alpha_2} \ln \left| \frac{\Gamma - \alpha_1}{\Gamma - \alpha_2} \right|, \quad (3.59)$$

$$\pm(\eta - \eta_0) = \frac{H}{\sqrt{(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)}} \ln \left| \frac{Y_2(\Gamma) - G_2(\Gamma)}{Y_2(\Gamma) + G_2(\Gamma)} \right|, \quad \alpha_1 > \alpha_2 > \alpha_3, \quad (3.60)$$

$$\pm(\eta - \eta_0) = \frac{2H}{\sqrt{(\alpha_1 - \alpha_3)(\alpha_2 - \alpha_4)}} F(\varphi_3, l_3), \quad \alpha_1 > \alpha_2 > \alpha_3 > \alpha_4, \quad (3.61)$$

where

$$Y_2(\Gamma) = \sqrt{(\Gamma - \alpha_2)(\alpha_1 - \alpha_3)}, \quad G_2(\Gamma) = \sqrt{(\Gamma - \alpha_3)(\alpha_1 - \alpha_2)}$$

and

$$\varphi_3 = \arcsin \sqrt{\frac{(\Gamma - \alpha_1)(\alpha_2 - \alpha_4)}{(\Gamma - \alpha_2)(\alpha_1 - \alpha_4)}}, \quad l_3^2 = \frac{(\alpha_2 - \alpha_3)(\alpha_1 - \alpha_4)}{(\alpha_1 - \alpha_3)(\alpha_2 - \alpha_4)}. \quad (3.62)$$

Also  $\alpha_1$ ,  $\alpha_2$ ,  $\alpha_3$  and  $\alpha_4$  are the roots of the polynomial equation

$$\Gamma^4 + \frac{\xi_3}{\xi_4}\Gamma^3 + \frac{\xi_2}{\xi_4}\Gamma^2 + \frac{\xi_1}{\xi_4}\Gamma + \frac{\xi_0}{\xi_4} = 0. \quad (3.63)$$

Substituting the solutions (3.57)-(3.61) into (2.4) and  $u = v^{\frac{2}{\gamma-1}}$ , we obtain the following traveling wave solutions of Eq. (1.2), respectively:

$$u(x, t) = \left( \tau_0 + \tau_1 \alpha_1 \pm \frac{\tau_1 H}{k(x - ct) - \eta_0} \right)^{\frac{2}{\gamma-1}}, \quad (3.64)$$

$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_1 + \frac{4H^2(\alpha_2 - \alpha_1)\tau_1}{4H^2 - [(\alpha_1 - \alpha_2)k(x - ct - \eta_0)]^2} \right\}^{\frac{2}{\gamma-1}}, \quad (3.65)$$

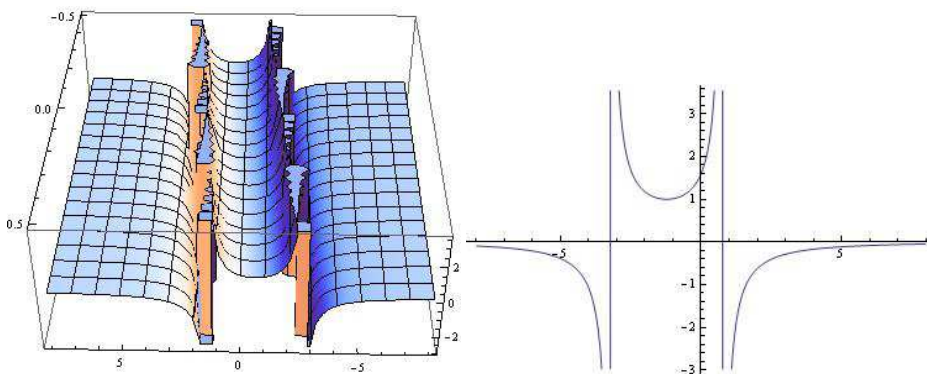
$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_2 + \frac{(\alpha_2 - \alpha_1)\tau_1}{\exp\left[\frac{k(\alpha_1 - \alpha_2)}{H}(x - ct - \eta_0)\right] - 1} \right\}^{\frac{2}{\gamma-1}}, \quad (3.66)$$

$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_1 + \frac{(\alpha_1 - \alpha_2)\tau_1}{\exp\left[\frac{k(\alpha_1 - \alpha_2)}{H}(x - ct - \eta_0)\right] - 1} \right\}^{\frac{2}{\gamma-1}}, \quad (3.67)$$

$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_1 - \frac{2(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)\tau_1}{2\alpha_1 - \alpha_2 - \alpha_3 + (\alpha_3 - \alpha_2) \cosh [A_4(x - ct)]} \right\}^{\frac{2}{\gamma-1}}, \quad (3.68)$$

$$u(x, t) = \left\{ \tau_0 + \tau_1 \alpha_2 + \frac{\tau_1(\alpha_1 - \alpha_2)(\alpha_4 - \alpha_2)}{\alpha_4 - \alpha_2 + (\alpha_1 - \alpha_4) \operatorname{sn}^2 [A_5(x - ct - \eta_0), l_3^2]} \right\}^{\frac{2}{\gamma-1}}, \quad (3.69)$$

where  $A_4 = \frac{k\sqrt{(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)}}{H}$  and  $A_5 = \mp \frac{k\sqrt{(\alpha_1 - \alpha_3)(\alpha_2 - \alpha_4)}}{2H}$ . If we take  $\tau_0 =$



**Figure 7.** The solution Eq.(3.70) is shown at  $\tau_0 = \tau_1 = \alpha_1 = \xi_4 = \zeta_0 = \beta = \delta = a = k = 1$ ,  $\eta_0 = 0$ ,  $\alpha_2 = 2$ ,  $\gamma = 3$  and the second graph represents the exact approximate solution of Eq. (3.70) for  $t = 1$ .

$-\tau_1 \alpha_1$  and  $\eta_0 = 0$ , then the solutions (3.64)-(3.68) can reduce to rational function solutions

$$u(x, t) = \left( \pm \frac{H\tau_1}{k(x - ct)} \right)^{\frac{2}{\gamma-1}}, \quad (3.70)$$

$$u(x, t) = \left\{ \frac{4H^2(\alpha_2 - \alpha_1)\tau_1}{4H^2 - [(\alpha_1 - \alpha_2)k(x - ct)]^2} \right\}^{\frac{2}{\gamma-1}}, \quad (3.71)$$

traveling wave solutions

$$u(x, t) = \left\{ \frac{(\alpha_2 - \alpha_1)\tau_1}{2} \left( 1 \mp \coth \left[ \frac{k(\alpha_1 - \alpha_2)}{2H} (x - ct) \right] \right) \right\}^{\frac{2}{\gamma-1}}, \quad (3.72)$$

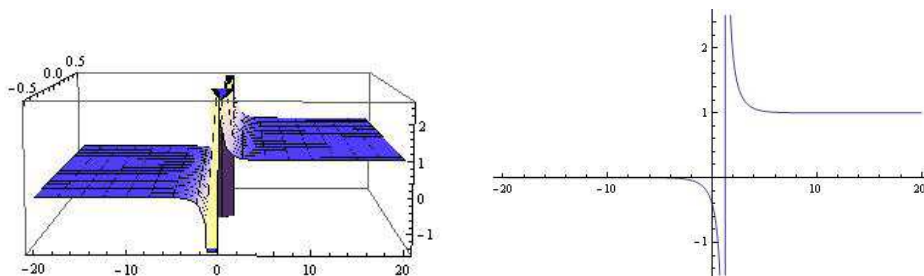
soliton solution

$$u(x, t) = \frac{A_6}{\left( D_1 + \cosh [A_4(x - ct)] \right)^{\frac{2}{\gamma-1}}}, \quad (3.73)$$

where  $A_6 = \left( \frac{2(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)\tau_1}{\alpha_3 - \alpha_2} \right)^{\frac{2}{\gamma-1}}$  and  $D_1 = \frac{2\alpha_1 - \alpha_2 - \alpha_3}{\alpha_3 - \alpha_2}$ . Here,  $A_6$  is the amplitude of the soliton, while  $c$  is the velocity and  $A_4$  is the inverse width of the soliton. Thus, we can say that the solitons exist for  $\tau_1 < 0$ . On the other hand, if we take  $\tau_0 = \tau_1 \alpha_2$  and  $\eta_0 = 0$ , the Jacobi elliptic function solution (3.69) can be written in the form

$$u(x, t) = \frac{A_6}{\left( D_2 + \operatorname{sn}^2 [A_5(x - ct), l_3^2] \right)^{\frac{2}{\gamma-1}}}, \quad (3.74)$$

where  $A_6 = \left( \frac{\tau_1(\alpha_1 - \alpha_2)(\alpha_4 - \alpha_2)}{\alpha_1 - \alpha_4} \right)^{\frac{2}{\gamma-1}}$  and  $D_2 = \frac{\alpha_4 - \alpha_2}{\alpha_1 - \alpha_4}$ .



**Figure 8.** The solution (3.71) is shown at  $\tau_0 = \tau_1 = \alpha_1 = \xi_4 = \zeta_0 = \beta = \delta = a = k = 1$ ,  $\eta_0 = 0$ ,  $\alpha_2 = 2$ ,  $\gamma = 3$  and the second graph represents the exact approximate solution of Eq. (3.71) for  $t = 1$ .

**Remark 3.4.** The traveling wave solutions (3.70)-(3.74) of Eq. (1.2) are new solutions that are not computed by any methods in the previous papers.

**Remark 3.5.** When the modulus  $l_3 \rightarrow 1$ , then the solution (3.74) can be reduced to the solitary wave solution

$$u(x, t) = \frac{A_6}{\left(D_2 + \tanh^2 [A_5(x - vt)]\right)^{\frac{2}{\gamma-1}}}, \quad (3.75)$$

where  $\alpha_3 = \alpha_4$ .

**Remark 3.6.** When the modulus  $l_3 \rightarrow 0$ , then the solution (3.74) can be converted into the compacton solution

$$u(x, t) = \frac{A_6}{\left(D_2 + \sin^2 [A_5(x - vt)]\right)^{\frac{2}{\gamma-1}}}, \quad (3.76)$$

where  $\alpha_2 = \alpha_3$ .

Case 2: If we take  $\epsilon = 1$ ,  $\delta = 1$  and  $\theta = 5$ , then

$$(v')^2 = \frac{\tau_1^2(\xi_5\Gamma^5 + \xi_4\Gamma^4 + \xi_3\Gamma^3 + \xi_2\Gamma^2 + \xi_1\Gamma + \xi_0)}{\zeta_0 + \zeta_1\Gamma}, \quad (3.77)$$

$$v'' = \frac{\tau_1 \left[ (\zeta_0 + \zeta_1\Gamma) (5\xi_5\Gamma^4 + 4\xi_4\Gamma^3 + 3\xi_3\Gamma^2 + 2\xi_2\Gamma + \xi_1) - \zeta_1\Phi_5(\Gamma) \right]}{2(\zeta_0 + \zeta_1\Gamma)^2}, \quad (3.78)$$

where  $\xi_5 \neq 0$ ,  $\zeta_1 \neq 0$  and  $\Phi_5(\Gamma) = \xi_5\Gamma^5 + \xi_4\Gamma^4 + \xi_3\Gamma^3 + \xi_2\Gamma^2 + \xi_1\Gamma + \xi_0$ . Respectively, solving the algebraic equation system (2.9) yields as follows:

$$\begin{aligned} \xi_0 &= -\frac{\zeta_0\xi_5\tau_0^2(\alpha + \gamma\alpha - 2\beta\tau_0^2)}{2\beta\zeta_1\tau_1^4}, & \xi_3 &= -\frac{\xi_5(\zeta_1(\alpha + \gamma\alpha - 12\beta\tau_0^2) - 8\beta\zeta_0\tau_0\tau_1)}{2\beta\zeta_1\tau_1^2}, \\ \xi_1 &= \frac{\xi_5\tau_0(\zeta_1\tau_0(2\beta\tau_0^2 - \alpha(\gamma + 1)) - 2\zeta_0\tau_1(\alpha + \gamma\alpha - 4\beta\tau_0^2))}{2\beta\zeta_1\tau_1^4}, \\ \xi_2 &= -\frac{\xi_5(2\zeta_1\tau_0(\alpha + \gamma\alpha - 4\beta\tau_0^2) + \zeta_0\tau_1(\alpha + \gamma\alpha - 12\beta\tau_0^2))}{2\beta\zeta_1\tau_1^3}, \end{aligned}$$

$$\xi_4 = \frac{\xi_5 (\zeta_0 \tau_1 + 4\zeta_1 \tau_0)}{\zeta_1 \tau_1}, \quad c = \pm \sqrt{\frac{2a^2 k^2 (\gamma + 1) \xi_5 + \beta (\gamma - 1)^2 \zeta_1 \tau_1^2}{2k^2 (\gamma + 1) \xi_5}}, \quad (3.79)$$

where  $\xi_5 = \xi_5$ ,  $\zeta_0 = \zeta_0$ ,  $\zeta_1 = \zeta_1$ ,  $\tau_0 = \tau_0$ ,  $\tau_1 = \tau_1$ . Substituting these results into Eqs. (2.5) and (2.10), we get

$$\pm (\eta - \eta_0) = \sqrt{\frac{\zeta_1}{\xi_5}} \int \sqrt{\frac{\Gamma + \frac{\zeta_0}{\zeta_1}}{\Gamma^5 + \frac{\xi_4}{\xi_5} \Gamma^4 + \frac{\xi_3}{\xi_5} \Gamma^3 + \frac{\xi_2}{\xi_5} \Gamma^2 + \frac{\xi_1}{\xi_5} \Gamma + \frac{\xi_0}{\xi_5}}} d\Gamma. \quad (3.80)$$

Integrating Eq. (3.80), we obtain the following exact approximate solutions to the Eq. (1.2).

When  $\Phi(\Gamma) = (\Gamma - \alpha_1)^5$ , we have

$$\pm (\eta - \eta_0) = -\frac{2H_1}{3\sqrt{\zeta_1}(\zeta_0 + \zeta_1 \alpha_1)} \left( \frac{\zeta_0 + \zeta_1 \Gamma}{\Gamma - \alpha_1} \right)^{\frac{3}{2}}. \quad (3.81)$$

If we take  $\Phi(\Gamma) = (\Gamma - \alpha_1)^4(\Gamma - \alpha_2)$  and  $\alpha_1 > \alpha_2$ , then we get

$$\pm (\eta - \eta_0) = \frac{-H_1}{\alpha_1 - \alpha_2} \left[ \frac{(\zeta_0 + \zeta_1 \alpha_2)}{2\sqrt{\zeta_1(\alpha_1 - \alpha_2)(\zeta_0 + \zeta_1 \alpha_1)}} \ln |Y_3(\Gamma)| + G_3(\Gamma) \right], \quad (3.82)$$

where

$$Y_3(\Gamma) = \frac{\Gamma - \alpha_1}{K(\Gamma) + \zeta_0(\alpha_1 - 2\alpha_2) - \zeta_1 \alpha_2 \alpha_1 + L(\Gamma)},$$

$$G_3(\Gamma) = \frac{1}{\Gamma - \alpha_1} \sqrt{\frac{(\zeta_0 + \zeta_1 \Gamma)(\Gamma - \alpha_2)}{\zeta_1}}$$

and

$$K(\Gamma) = (\zeta_0 + 2\zeta_1 \alpha_1 - \zeta_1 \alpha_2) \Gamma, \quad L(\Gamma) = 2\sqrt{(\zeta_0 + \zeta_1 \Gamma)(\zeta_0 + \zeta_1 \alpha_1)(\Gamma - \alpha_2)(\alpha_1 - \alpha_2)}.$$

When  $\Phi(\Gamma) = (\Gamma - \alpha_1)^3(\Gamma - \alpha_2)^2$  and  $\alpha_1 > \alpha_2$ , we obtain

$$\pm (\eta - \eta_0) = \frac{-2H_1}{\alpha_1 - \alpha_2} \left[ Y_4(\Gamma) + \sqrt{\frac{\zeta_0 + \zeta_1 \alpha_2}{\zeta_1(\alpha_1 - \alpha_2)}} \arctan(G_4(\Gamma)) \right], \quad (3.83)$$

where

$$Y_4(\Gamma) = \sqrt{\frac{\zeta_0 + \zeta_1 \Gamma}{\zeta_1(\Gamma - \alpha_1)}}, \quad G_4(\Gamma) = \sqrt{\frac{(\Gamma - \alpha_1)(\zeta_0 + \zeta_1 \alpha_2)}{(\alpha_1 - \alpha_2)(\zeta_0 + \zeta_1 \Gamma)}}.$$

If we take  $\Phi(\Gamma) = (\Gamma - \alpha_1)^2(\Gamma - \alpha_2)^2(\Gamma - \alpha_3)$  and  $\alpha_1 > \alpha_2 > \alpha_3$ , then we get

$$\pm (\eta - \eta_0) = \frac{-H_1}{(\alpha_1 - \alpha_3)\sqrt{\zeta_1}} [Y_5(\Gamma) + G_5(\Gamma)], \quad (3.84)$$

where

$$Y_5(\Gamma) = Y \ln \left| \frac{\alpha_2 - \Gamma}{P(\Gamma) + \zeta_0(\alpha_2 - 2\alpha_3) - \zeta_1\alpha_2\alpha_3 + Q(\Gamma)} \right|,$$

$$G_5(\Gamma) = Z \ln \left| \frac{R(\Gamma) + \zeta_0(\alpha_1 - 2\alpha_3) - \zeta_1\alpha_1\alpha_3 + S(\Gamma)}{\Gamma - \alpha_2} \right|,$$

$$Y = \sqrt{\frac{\zeta_0 + \zeta_1\alpha_2}{\alpha_2 - \alpha_3}}, \quad Z = \sqrt{\frac{\zeta_0 + \zeta_1\alpha_1}{\alpha_1 - \alpha_3}},$$

$$P(\Gamma) = 2\sqrt{(\zeta_0 + \zeta_1\Gamma)(\zeta_0 + \zeta_1\alpha_2)(\Gamma - \alpha_3)(\alpha_2 - \alpha_3)}, Q(\Gamma) = (\zeta_0 + 2\zeta_1\alpha_2 - \zeta_1\alpha_3)\Gamma, \quad (3.85)$$

$$R(\Gamma) = 2\sqrt{(\zeta_0 + \zeta_1\Gamma)(\zeta_0 + \zeta_1\alpha_1)(\Gamma - \alpha_3)(\alpha_1 - \alpha_3)}, S(\Gamma) = (\zeta_0 + 2\zeta_1\alpha_1 - \zeta_1\alpha_3)\Gamma. \quad (3.86)$$

When  $\Phi(\Gamma) = (\Gamma - \alpha_1)^3(\Gamma - \alpha_2)(\Gamma - \alpha_3)$  and  $\alpha_1 > \alpha_2 > \alpha_3$ , then we obtain

$$\pm(\eta - \eta_0) = \frac{-2H_1}{\alpha_1 - \alpha_3} \sqrt{\frac{\zeta_0 + \zeta_1\alpha_3}{\zeta_1(\alpha_1 - \alpha_2)}} E(\varphi_4, l_4), \quad (3.87)$$

where

$$E(\varphi_4, l_4) = \int_0^{\varphi_4} \sqrt{1 - l_4^2 \sin^2 \psi} d\psi,$$

$$\varphi_4 = \arcsin \sqrt{\frac{(\Gamma - \alpha_3)(\alpha_2 - \alpha_1)}{(\Gamma - \alpha_1)(\alpha_2 - \alpha_3)}}, \quad l_4^2 = \frac{(\alpha_3 - \alpha_2)(\zeta_0 + \zeta_1\alpha_1)}{(\alpha_1 - \alpha_2)(\zeta_0 + \zeta_1\alpha_3)}. \quad (3.88)$$

If we take  $\Phi(\Gamma) = (\Gamma - \alpha_1)^2(\Gamma - \alpha_2)(\Gamma - \alpha_3)(\Gamma - \alpha_4)$  and  $\alpha_1 > \alpha_2 > \alpha_3 > \alpha_4$ , then we get

$$\pm(\eta - \eta_0) = H_2 \left( \frac{\zeta_0 + \zeta_1\Gamma}{\alpha_1 - \alpha_4} \pi(\varphi_5, n, l_5) - \frac{\zeta_0 + \zeta_1\alpha_2}{\alpha_2 - \alpha_4} F(\varphi_5, l_5) \right), \quad (3.89)$$

where

$$H_1 = \sqrt{\frac{\zeta_1}{\xi_5}}, \quad H_2 = \frac{2H_1(\alpha_2 - \alpha_4)}{(\alpha_1 - \alpha_2)\sqrt{\zeta_1(\alpha_2 - \alpha_3)(\zeta_0 + \zeta_1\alpha_4)}},$$

$$\pi(\varphi_5, n, l_5) = \int_0^{\varphi_5} \frac{d\psi}{(1 + n \sin^2 \psi)\sqrt{1 - l_5^2 \sin^2 \psi}}, \quad n = -\frac{(\alpha_1 - \alpha_2)(\alpha_3 - \alpha_4)}{(\alpha_2 - \alpha_3)(\alpha_1 - \alpha_4)} \quad (3.90)$$

and

$$\varphi_5 = \arcsin \sqrt{\frac{(\Gamma - \alpha_4)(\alpha_3 - \alpha_2)}{(\Gamma - \alpha_2)(\alpha_3 - \alpha_4)}}, \quad l_5^2 = \frac{(\alpha_4 - \alpha_3)(\zeta_0 + \zeta_1\alpha_2)}{(\alpha_2 - \alpha_3)(\zeta_0 + \zeta_1\alpha_4)}. \quad (3.91)$$

Case 3: If we take  $\epsilon = 0$ ,  $\delta = 2$  and  $\theta = 6$ , then

$$(v')^2 = \frac{(\tau_1 + 2\tau_2\Gamma)^2(\xi_6\Gamma^6 + \xi_5\Gamma^5 + \xi_4\Gamma^4 + \xi_3\Gamma^3 + \xi_2\Gamma^2 + \xi_1\Gamma + \xi_0)}{\zeta_0}, \quad (3.92)$$

$$v'' = \frac{4\tau_2(\Phi_6(\Gamma)) + (\tau_1 + 2\tau_1\Gamma)(6\xi_6\Gamma^5 + 5\xi_5\Gamma^4 + 4\xi_4\Gamma^3 + 3\xi_3\Gamma^2 + 2\xi_2\Gamma + \xi_1\Gamma)}{2\zeta_0}, \quad (3.93)$$

where  $\xi_6 \neq 0$ ,  $\zeta_0 \neq 0$  and  $\Phi_6(\Gamma) = \xi_6\Gamma^6 + \xi_5\Gamma^5 + \xi_4\Gamma^4 + \xi_3\Gamma^3 + \xi_2\Gamma^2 + \xi_1\Gamma + \xi_0$ . Respectively, solving the algebraic equation system (2.9) yields as follows:

$$\begin{aligned} \xi_0 &= \frac{\xi_6\tau_1^2(\beta\tau_1^4 - 8\alpha(\gamma + 1)\tau_2^2)}{64\beta\tau_2^6}, & \xi_1 &= \frac{\xi_6\tau_1(3\beta\tau_1^4 - 8\alpha(\gamma + 1)\tau_2^2)}{16\beta\tau_2^5}, \\ \xi_2 &= \frac{\xi_6(15\beta\tau_1^4 - 8\alpha(\gamma + 1)\tau_2^2)}{16\beta\tau_2^4}, & \xi_3 &= \frac{5\xi_6\tau_1^3}{2\tau_2^2}, & \xi_4 &= \frac{15\xi_6\tau_1^2}{4\tau_2^2}, & \xi_5 &= \frac{3\xi_6\tau_1}{\tau_2}, \\ \tau_0 &= \frac{\tau_1^2}{4\tau_2}, & c &= \pm\sqrt{\frac{8a^2k^2(\gamma + 1)\xi_6 + \beta(\gamma - 1)^2\zeta_0\tau_2^2}{8k^2(\gamma + 1)\xi_6}}, \end{aligned} \tag{3.94}$$

where  $\xi_6$ ,  $\tau_1$ ,  $\tau_2$  and  $\zeta_0$  are free parameters. Substituting these results into Eqs. (2.5) and (2.10), we get

$$\pm(\eta - \eta_0) = H_3 \int \frac{d\Gamma}{\sqrt{\Gamma^6 + \frac{\xi_5}{\xi_6}\Gamma^5 + \frac{\xi_4}{\xi_6}\Gamma^4 + \frac{\xi_3}{\xi_6}\Gamma^3 + \frac{\xi_2}{\xi_6}\Gamma^2 + \frac{\xi_1}{\xi_6}\Gamma + \frac{\xi_0}{\xi_6}}}, \tag{3.95}$$

where  $H_3 = \sqrt{\frac{\zeta_0}{\xi_6}}$ . Integrating Eq. (3.95), we obtain the solutions to the Eq. (1.2) as follows:

$$\pm(\eta - \eta_0) = -\frac{H_3}{2(\Gamma - \alpha_1)^2}, \tag{3.96}$$

$$\pm(\eta - \eta_0) = \frac{2H_3(2\Gamma - 3\alpha_1 + \alpha_2)}{3(\alpha_1 - \alpha_2)^2} \sqrt{\frac{\Gamma - \alpha_2}{(\Gamma - \alpha_1)^3}}, \quad \alpha_1 > \alpha_2, \tag{3.97}$$

$$\pm(\eta - \eta_0) = \frac{H_3 \left( \alpha_2 - \alpha_1 \left( \ln \left| \frac{\Gamma - \alpha_2}{\Gamma - \alpha_1} \right| + 1 \right) - \Gamma \ln \left| \frac{\Gamma - \alpha_1}{\Gamma - \alpha_2} \right| \right)}{(\Gamma - \alpha_1)(\alpha_1 - \alpha_2)^2}, \tag{3.98}$$

$$\pm(\eta - \eta_0) = \frac{-2H_3(2\Gamma - \alpha_1 - \alpha_2)}{(\alpha_1 - \alpha_2)^2 \sqrt{(\Gamma - \alpha_1)(\Gamma - \alpha_2)}}, \tag{3.99}$$

$$\pm(\eta - \eta_0) = \frac{-H_3 \left( \alpha_1 \ln \left| \frac{\Gamma - \alpha_2}{\Gamma - \alpha_3} \right| + \alpha_2 \ln \left| \frac{\Gamma - \alpha_3}{\Gamma - \alpha_1} \right| + \alpha_3 \ln \left| \frac{\Gamma - \alpha_1}{\Gamma - \alpha_2} \right| \right)}{(\alpha_1 - \alpha_2)(\alpha_2 - \alpha_3)(\alpha_1 - \alpha_3)}, \quad \alpha_1 > \alpha_2 > \alpha_3, \tag{3.100}$$

$$\pm(\eta - \eta_0) = H_3 \left( \frac{\sqrt{(\Gamma - \alpha_1)(\Gamma - \alpha_3)}}{(\Gamma - \alpha_2)(\alpha_1 - \alpha_2)(\alpha_2 - \alpha_3)} + \frac{(\alpha_1 - 2\alpha_2 + \alpha_3)i \log(V(\Gamma))}{2(\alpha_1 - \alpha_2)^{\frac{3}{2}}(\alpha_1 - \alpha_2)^{\frac{3}{2}}} \right), \tag{3.101}$$

where

$$\begin{aligned} V(\Gamma) &= \frac{-4(\alpha_1 - \alpha_2)(\alpha_2 - \alpha_3)\sqrt{(\Gamma - \alpha_1)(\Gamma - \alpha_3)}}{(\Gamma - \alpha_2)(\alpha_1 - 2\alpha_2 + \alpha_3)} \\ &+ \frac{2i\sqrt{(\alpha_1 - \alpha_2)(\alpha_2 - \alpha_3)}(\alpha_1(\Gamma + \alpha_2 - 2\alpha_3) - 2\Gamma\alpha_2 + \alpha_3(\Gamma + \alpha_2))}{(\Gamma - \alpha_2)(\alpha_1 - 2\alpha_2 + \alpha_3)}, \\ \pm(\eta - \eta_0) &= H_3 \left( \frac{2\sqrt{\frac{\Gamma - \alpha_1}{\Gamma - \alpha_2}}}{(\alpha_1 - \alpha_2)(\alpha_2 - \alpha_3)} - \frac{2 \arctan \left[ \frac{(\Gamma - \alpha_1)(\alpha_3 - \alpha_2)}{(\Gamma - \alpha_2)(\alpha_1 - \alpha_3)} \right]}{(\alpha_2 - \alpha_3)\sqrt{(\alpha_1 - \alpha_3)(\alpha_3 - \alpha_2)}} \right), \end{aligned} \tag{3.102}$$



$$\pm(\eta - \eta_0) = Y_6(G_6(\Gamma) + MF(\varphi_5, l_5) + N[(\alpha_1 - \alpha_4)F(\varphi_5, l_5) - (\alpha_2 - \alpha_4)E(\varphi_5, l_5)]), \quad (3.103)$$

where

$$\begin{aligned} Y_6 &= \frac{2H_3}{(\alpha_2 - \alpha_3)(\alpha_3 - \alpha_4)}, & G_6(\Gamma) &= \sqrt{\frac{(\Gamma - \alpha_2)(\Gamma - \alpha_4)}{(\Gamma - \alpha_1)(\Gamma - \alpha_3)}}, \\ M &= \frac{\alpha_1 - \alpha_2 + \alpha_3 - \alpha_4}{\sqrt{(\alpha_1 - \alpha_4)(\alpha_2 - \alpha_3)}}, & N &= \frac{1}{(\alpha_1 - \alpha_3)\sqrt{(\alpha_2 - \alpha_4)}}, \\ \varphi_5 &= \arcsin \sqrt{\frac{(\Gamma - \alpha_2)(\alpha_1 - \alpha_4)}{(\Gamma - \alpha_1)(\alpha_2 - \alpha_4)}}, & l_5^2 &= \frac{(\alpha_1 - \alpha_3)(\alpha_2 - \alpha_4)}{(\alpha_2 - \alpha_3)(\alpha_1 - \alpha_4)}, \end{aligned} \quad (3.104)$$

$$\pm(\eta - \eta_0) = \frac{-H_3(\Gamma - \alpha_3)}{\Gamma - \alpha_4} \left( \frac{\log(Y_7(\Gamma))}{\sqrt{(\alpha_1 - \alpha_4)(\alpha_2 - \alpha_4)}} + \frac{i \log(G_7(\Gamma))}{\sqrt{(\alpha_1 - \alpha_3)(\alpha_3 - \alpha_2)}} \right) \quad (3.105)$$

$$\begin{aligned} \text{where } Y_7(\Gamma) &= \frac{-\Gamma + \alpha_4}{2\sqrt{(\Gamma - \alpha_1)(\Gamma - \alpha_2)(\alpha_1 - \alpha_4)(\alpha_2 - \alpha_4) + (2\alpha_4 - \alpha_2 - \alpha_1)\Gamma - \alpha_2\alpha_4 + 2\alpha_1\alpha_2 - \alpha_1\alpha_4}}, \\ G_7(\Gamma) &= \frac{-(\alpha_3 - \alpha_4)(2\sqrt{(\Gamma - \alpha_1)(\Gamma - \alpha_2)(\alpha_1 - \alpha_3)(\alpha_3 - \alpha_2)} - i(-2\Gamma\alpha_3 + \alpha_2(\Gamma + \alpha_3) + \alpha_1(\Gamma - 2\alpha_2 + \alpha_3)))}{\sqrt{(\alpha_1 - \alpha_3)(\alpha_3 - \alpha_2)(-\Gamma + \alpha_4)}}, \end{aligned}$$

$$\pm(\eta - \eta_0) = H_4 \left( \frac{\pi(\varphi_6, n, l_6)}{(\alpha_2 - \alpha_4)} + \frac{F(\varphi_6, l_6)}{(\alpha_1 - \alpha_2)} \right), \quad \alpha_1 > \alpha_2 > \alpha_3 > \alpha_4 > \alpha_5, \quad (3.106)$$

where

$$\begin{aligned} H_4 &= \frac{2H_3}{\sqrt{(\alpha_2 - \alpha_3)(\alpha_1 - \alpha_5)}}, & \varphi_6 &= \arcsin \sqrt{\frac{(\Gamma - \alpha_2)(\alpha_1 - \alpha_5)}{(\Gamma - \alpha_1)(\alpha_2 - \alpha_5)}}, \\ l_6^2 &= \frac{(\alpha_1 - \alpha_3)(\alpha_2 - \alpha_5)}{(\alpha_2 - \alpha_3)(\alpha_1 - \alpha_5)}, & n &= \frac{(\alpha_1 - \alpha_4)(\alpha_2 - \alpha_5)}{(\alpha_2 - \alpha_4)(\alpha_1 - \alpha_5)}. \end{aligned} \quad (3.107)$$

Also  $\alpha_1, \alpha_2, \alpha_3, \alpha_4, \alpha_5$ , and  $\alpha_6$  are the roots of the polynomial equation

$$\Gamma^6 + \frac{\xi_5}{\xi_6}\Gamma^5 + \frac{\xi_4}{\xi_6}\Gamma^4 + \frac{\xi_3}{\xi_6}\Gamma^3 + \frac{\xi_2}{\xi_6}\Gamma^2 + \frac{\xi_1}{\xi_6}\Gamma + \frac{\xi_0}{\xi_6} = 0. \quad (3.108)$$

Substituting the solutions (3.96)-(3.103) and (3.105)-(3.106) into (2.4) and (3.2), we have

$$u(x, t) = \left( \tau_0 + \tau_1\alpha_1 \pm \tau_1 \sqrt{\pm \frac{H_3}{2k(x \pm ct - \eta_0)}} + \tau_2 \left( \alpha_1 \pm \sqrt{\pm \frac{H_3}{2k(x \pm ct - \eta_0)}} \right)^2 \right)^{\frac{2}{\gamma-1}}, \quad (3.109)$$

$$u(x, t) = \left[ \tau_0 + \tau_1(\alpha_1 - W - 2T) + \tau_2(\alpha_1 - W - 2T)^2 \right]^{\frac{2}{\gamma-1}}, \quad (3.110)$$

$$u(x, t) = \left[ \tau_0 + \tau_1 \left( \alpha_1 + W + (1 - i\sqrt{3})T \right) + \tau_2 \left( \alpha_1 + W + (1 - i\sqrt{3})T \right)^2 \right]^{\frac{2}{\gamma-1}}, \quad (3.111)$$

$$u(x, t) = \left[ \tau_0 + \tau_1 \left( \alpha_1 - W_1 + (1 + i\sqrt{3})T \right) + \tau_2 \left( \alpha_1 - W_1 + (1 + i\sqrt{3})T \right)^2 \right]^{\frac{2}{\gamma-1}}, \quad (3.112)$$

where

$$\begin{aligned}
 W &= \frac{4^{\frac{1}{3}}(1+i\sqrt{3})H_3^2(\alpha_1-\alpha_1)^2}{\left(H_3^2(\alpha_1-\alpha_1)^3H_5^2+3H_3^2(\eta-\eta_0)(\alpha_1-\alpha_2)^5\sqrt{H_3^3}\right)^{\frac{1}{3}}}, \\
 T &= \frac{\left(H_3^2(\alpha_1-\alpha_1)^3H_5^2+3H_3^2(\eta-\eta_0)(\alpha_1-\alpha_2)^5\sqrt{H_3^3}\right)^{\frac{1}{3}}}{H_5}, \\
 W_1 &= \frac{2}{1+i\sqrt{3}}W, \quad H_5 = 16H_3^2 - 9(\alpha_1 - \alpha_2)^4(\eta - \eta_0)^2, \\
 u(x, t) &= \left[ \tau_0 + \tau_1 \left( \frac{(\alpha_1 + \alpha_2)H_6 \pm (\alpha_1 - \alpha_3)^3(\eta - \eta_0)\sqrt{-H_6}}{2H_6} \right) \right] \quad (3.113)
 \end{aligned}$$

$$+ \tau_2 \left( \frac{(\alpha_1 + \alpha_2)H_6 \pm (\alpha_1 - \alpha_3)^3(\eta - \eta_0)\sqrt{-H_6}}{2H_6} \right)^2 \Big]^{\frac{2}{\gamma-1}}, \quad (3.114)$$

where

$$H_6 = 16H_3^2 - (\alpha_1 - \alpha_2)^4(\eta - \eta_0)^2.$$

For simplicity, we can write the solutions (3.109) and (3.114) as follows:

$$u(x, t) = \left[ \sum_{i=0}^2 \tau_i \left( \alpha_1 \pm \sqrt{\pm \frac{H_3}{2k(x \pm \sqrt{\frac{8a^2k^2(\gamma+1)\xi_6 + \beta(\gamma-1)^2\zeta_0\tau_2^2}{8k^2(\gamma+1)\xi_6}}t - \eta_0)}} \right)^i \right]^{\frac{2}{\gamma-1}}, \quad (3.115)$$

$$u(x, t) = \left[ \sum_{i=0}^2 \tau_i \left( \frac{(\alpha_1 + \alpha_2)H_6 \pm (\alpha_1 - \alpha_3)^3(\eta - \eta_0)\sqrt{-H_6}}{2H_6} \right)^i \right]^{\frac{2}{\gamma-1}}. \quad (3.116)$$

**Remark 3.7.** The hyperbolic function solutions of the generalized Klein-Gordon equation was also found by the exp-function method [2]. In this study, we obtain some new classifications of the exact solutions to Eq. (1.2), such as rational function solutions, Jacobi elliptic function solutions, elliptic integral  $F, E$  and  $\Pi$  function solutions.

### 4. Conclusion

In this study, we studied the extended trial equation method to establish traveling wave solutions to generalized nonlinear evolution equations arising in applied physics and engineering. Some new exact solutions for the GRLW equation and generalized Klein-Gordon equation have been successfully found. Besides, the extended trial equation method is based on the elliptic differential equation. Also, we discussed a new trial equation method. We think that the idea introduced in this paper can be applied to other nonlinear partial differential equations.

#### Competing Interests

The authors declare that they have no competing interests.

#### Authors' Contributions

All authors contributed equally to the manuscript and read and approved of the final draft.

## References

- [1] M. A. Abdou and E. M. Abulwafa, *Application of the Exp-Function method to the Riccati equation and new exact solutions with three arbitrary functions of quantum Zakharov equations*, Z. Naturforsch., 63a(2008), 646–652.
- [2] A. H. A. Ali, A. A. Soliman, and K. R. Raslan, *Soliton solution for nonlinear partial differential equations by cosine-function method*, Phys. Lett., A 368(2007), 299–304.
- [3] M. T. Alquran, *Solitons and periodic solutions to nonlinear partial differential equations by the sine-cosine method*, Appl. Math. Inf. Sci., 6(2012), 85–88.
- [4] H. Bulut, Y. Pandir and S.T. Demiray, *Exact solutions of nonlinear Schrodinger's equation with dual power-law nonlinearity by extended trial equation method*, Waves in Random and Complex Media, 24(2014)(4), 439–451.
- [5] Z. D. Dai, C. J. Wang, S. Q. Lin, D. L. Li, and G. Mu, *The three-wave method for nonlinear evolution equations*, Nonl. Sci. Lett., A1(2010)(1), 77–82.
- [6] X. H. Du, *An irrational trial equation method and its applications*, Pramana-J. Phys., 75(2010), 415–422.
- [7] A. Ebaid, *Exact solutions for the generalized Klein-Gordon equation via a transformation and Exp-function method and comparison with Adomian's method*, J. Comput. Appl. Math., 223(2009), 278–290.
- [8] G. Ebadi, E. V. Krishnan, and A. Biswas, *Solitons and cnoidal waves of the Klein-Gordon-Zakharov equation in plasmas*, Pramana-J. Phys., 79(2012), 185–198.
- [9] M. K. Elboree, *Hyperbolic and trigonometric solutions for some nonlinear evolution equations*, Commun. Nonl. Sci. Numer. Simulat., 17(2012), 4085–4096.
- [10] Y. Gurefe and E. Misirli, *New variable separation solutions of two-dimensional Burgers system*, Appl. Math. Comput., 217(2011), 9189–9197.
- [11] Y. Gurefe, E. Misirli, A. Sonmezoglu, and M. Ekici, *Extended trial equation method to generalized nonlinear partial differential equations*, Appl. Math. Comput., 219(2013), 5253–5260.
- [12] Y. Gurefe, A. Sonmezoglu, and E. Misirli, *Application of the trial equation method for solving some nonlinear evolution equations arising in mathematical physics*, Pramana-J. Phys., 7(2011), 1023–1029.
- [13] J. H. He, *Asymptotic methods for solitary solutions and compactons*, Abstr. Appl. Anal., 2012(2012), 130 pages.
- [14] H. Jia and W. Xu, *Solitons solutions for some nonlinear evolution equations*, Appl. Math. Comput., 217(2010), 1678–1687.
- [15] N. A. Kudryashov, *One method for finding exact solutions of nonlinear differential equations*, Commun. Nonl. Sci. Numer. Simulat., 17(2012), 2248–2253.
- [16] C. S. Liu, *Trial equation method and its applications to nonlinear evolution equations*, Acta. Phys. Sin., 54(2005), 2505–2509.
- [17] C. S. Liu, *A new trial equation method and its applications*, Commun. Theor. Phys., 45(2006), 395–397.

- [18] C. S. Liu, *Applications of complete discrimination system for polynomial for classifications of traveling wave solutions to nonlinear differential equations*, Comput. Phys. Commun., 181(2010), 317–324.
- [19] J. Liu, G. Mua, Z. Dai, and X. Liu, *Analytic multi-soliton solutions of the generalized Burgers equation*, Comput. Math. Appl., 61(2011), 1995–1999.
- [20] W. X. Ma, T. Huang, and Y. Zhang, *A multiple exp-function method for nonlinear differential equations and its application*, Phys. Scr., 82(2010), 065003, 8 pages.
- [21] J. Nickel and H. W. Schurmann, *2-soliton-solution of the Novikov-Veselov equation*, Int. J. Theor. Phys., 45(2006), 1825–1829.
- [22] Y. Pandir, Y. Gurefe, U. Kadak, and E. Misirli, *Classifications of exact solutions for some nonlinear partial differential equations with generalized evolution*, Abstr. Appl. Anal., 2012(2012), 16 pages.
- [23] Y. Pandir, Y. Gurefe, and E. Misirli, *Classification of exact solutions to the generalized Kadomtsev-Petviashvili equation*, Phys. Scripta, 87(2013), 025003 p12.
- [24] Y. Pandir, *New exact solutions of the generalized Zakharov-Kuznetsov modified equal-width equation*, Pramana-J. Phys., 82(2014)(6), 949–964.
- [25] Y. Pandir, Y. Gurefe, and E. Misirli, *A new approach to Kudryashov's method for solving some nonlinear physical models*, Int. J. Phys. Sci., 7(2012), 2860–2866.
- [26] P. N. Ryabov, D. I. Sinelshchikov, and M. B. Kochanov, *Application of the Kudryashov method for finding exact solutions of the high order nonlinear evolution equations*, Appl. Math. Comput., 218(2011), 3965–3972.
- [27] Y. Shi, Z. Dai, and D. Li, *Application of Exp-function method for 2D cubic-quintic Ginzburg-Landau equation*, Appl. Math. Comput., 210(2009), 269–275.
- [28] A. M. Wazwaz, *Special types of the nonlinear dispersive Zakharov-Kuznetsov equation with compactons, solitons and periodic solutions*, Int. J. Comput. Math., 81(2004)(81), 1107–1119.
- [29] Y. Xie and J. Tang, *The superposition method in seeking the solitary wave solutions to the KdV-Burgers equation*, Pramana-J. Phys., 66(2006), 479–483.
- [30] J. R. Yang and J. J. Mao, *Soliton solutions of coupled KdV system from Hirota's bilinear direct method*, Commun. Theor. Phys., 49(2008), 22–26.
- [31] E. Zayed, M. Abdelaziz, and M. Elmalky, *Enhanced  $(G'/G)$ -expansion method and applications to the  $(2+1)D$  typical breaking soliton and Burgers equations*, J. Adv. Math. Stud., 4(2011), 109–122.