

BEST PROXIMITY POINTS FOR WEAK PROXIMAL ENRICHED G –CONTRACTIONS IN GRAPHICAL CONVEX METRIC SPACES

Chaobo Li^{1,†}, Yunan Cui¹ and Rizwan Anjum²

Abstract In this paper, we redefine the concept of a graphical convex metric space involving sets with a graphical structure, and a new class of non-self mappings, called weak proximal enriched G –contractions, is introduced in the aforementioned space. Moreover, we demonstrate the existence of best approximation points for two types of weak proximal enriched G –contractions in graphical convex metric spaces, under suitable control conditions. Additionally, we provide examples to confirm our main results.

Keywords graphical convex metric space, weak enriched G –contraction, best proximity point, directed graph

MSC(2010) 47H09, 47H10.

1. Introduction

Let X be a nonempty set and $T : X \rightarrow X$ be a mapping, an element $u \in X$ is called a fixed point of T if $u = Tu$. Fixed point theory play a crucial role in nonlinear functional analysis. In 1922, Banach developed the Banach contraction principle [1], which was a fundamental consequence of fixed point theory on metric spaces. The Banach contraction principle states that any self-mapping T of a complete metric space (X, d) satisfies the condition

$$d(Tu, Tv) \leq kd(u, v), 0 \leq k < 1$$

for all $u, v \in X$, then T has a unique fixed point in X . After that many authors have generalized, improved and extended this celebrated result by changing either the conditions of the mappings or the construction of the space [2–11].

The weak contraction principle, initially formulated by Alber and Guerr [12], in Hilbert spaces, serves as a generalization of Banach’s contraction principle. Rhoades [13] later extended this principle to metric spaces. A selfmap T of X is weakly contractive if, for every $u, v \in X$,

$$d(Tu, Tv) \leq d(u, v) - \eta(d(u, v))$$

[†]The corresponding author.

¹Department of Mathematics, Harbin University of Science and Technology, Harbin, 150080, China;

²Department of Mathematics, Division of Science and Technology, University of Education, Lahore 54770, Pakistan;

Email: lichaobo6898@163.com(C.L.), cuiya@hrbust.edu.cn(Y.C.), rizwan.anjum@ue.edu.pk(R.A.).

where $\eta : [0, \infty) \rightarrow [0, \infty)$ is continuous and nondecreasing such that $\eta(t) = 0$ if and only if $t = 0$. Recently, Berinde and Păcurar [14] introduced a new class of enriched contractions, which includes the Banach contractions. A mapping $T : X \rightarrow X$ is called an enriched contraction mapping or a (a, b) -enriched enriched contraction mapping if there exist $a \in [0, \infty)$ and $b \in [0, a + 1)$ such that

$$\|a(u - v) + Tu - Tv\| \leq b\|u - v\|.$$

In [14], they obtained the following theorem.

Theorem 1.1. [14] *Let $(X, \|\cdot\|)$ be a Banach space and $T : X \rightarrow X$ be an enriched contraction mapping. Then*

- (1) $F(T) = \{u\}$, for some $u \in X$;
- (2) there exists $\alpha \in [0, 1)$ such that the sequence $\{u_n\}_{n=0}^{\infty}$ defined by

$$u_{n+1} = \alpha u_n + (1 - \alpha)Tu_n$$

converges to u .

- (3) the following estimate:

$$\|u_{n+i-1} - p\| \leq \frac{\mu^i}{1 - \mu} \|u_n - u_{n-1}\|$$

for any $n \in \mathbb{N}$, where $\mu = \frac{k}{1-k}$.

In 1970, Takahashi [15] introduced the concepts of the convex structure and the convex metric space.

Definition 1.1. [15] Let (X, d) be a metric space. A mapping $W : X \times X \times [0, 1] \rightarrow X$ is said to be a convex structure on X if for any $z \in X$ and $(u, v; \lambda) \in X \times X \times [0, 1]$,

$$d(z, W(u, v; \lambda)) \leq \lambda d(z, u) + (1 - \lambda)d(z, v), \quad (1.1)$$

then the space (X, d, W) is called a convex metric space.

A nonempty subset H of a convex metric space (X, d, W) is said to be convex if $W(u, v; \lambda) \in H$ for all $u, v \in H$ and $\lambda \in [0, 1]$. It is clear that every linear normed space, along with each of its convex subsets, can be considered as a convex metric space, utilizing the natural convex structure,

$$W(u, v; \lambda) = \lambda u + (1 - \lambda)v,$$

but the reverse is not valid [16–18].

Berinde and Păcurar [18] gave the concept of enriched contractions on a convex metric space as below.

Definition 1.2. [18] Let (X, d, W) be a convex metric space. A mapping $T : X \rightarrow X$ is said to be an enriched contraction if there exists $k \in [0, 1)$ such that

$$d(W(u, Tu; \lambda), W(v, Tv; \lambda)) \leq kd(u, v)$$

for all $u, v \in X$.

Lemma 1.1. [18] *Let (X, d, W) be a convex metric space and $T : X \rightarrow X$ be a mapping. Define the mapping $T_\lambda : X \rightarrow X$ by*

$$T_\lambda u = W(u, Tu; \lambda), u \in X,$$

then for any $\lambda \in [0, 1)$, we have $F(T) = F(T_\lambda)$.

In 2006, Espinola and Kirk [19] presented valuable findings that integrated fixed point theory with graph theory. Let X be a nonempty set. The graph G on X is an ordered pair $(V(G), E(G))$, where the vertex set $V(G)$ of G is X and the edge $E(G)$ of X is a subset of the Cartesian product $X \times X$. Each edge in the graph G can be assigned a weight equivalent to the distance between its vertices, thereby transforming it into a weighted graph. Later on, Jachymski [20] replaced the partial order with a directed graph. He introduced the following mapping: a self-mapping T of a complete metric space (X, d) is called a G -contraction if there exists $k \in (0, 1)$ such that for all $u, v \in X$ with $(u, v) \in E(G)$, the following two conditions hold:

- (1) $(Tu, Tv) \in E(G)$;
- (2) $d(Tu, Tv) \leq kd(u, v)$.

The graph G is called reflexive, if set $E(G)$ contains all loops, that is, $(u, u) \in E(G)$ for all $u \in X$. Furthermore, a graph G is called transitive whenever $(u, v) \in E(G)$ and $(v, z) \in E(G)$ implies $(u, z) \in E(G)$.

On the other hand, as a non-self mapping T may not have a fixed point, there is often an attempt to find an element u that is in some sense closest to Tu . In this context, best approximation theorems and best proximity point theorems are relevant. Let A, B be two nonempty subsets of a metric space (X, d) and $T : A \rightarrow B$ be a non-self mapping. A point $q \in A$ is called a best proximity point of T if $d(q, Tq) = d(A, B)$, where

$$d(A, B) = \inf \{d(u, v) : u \in A, v \in B\}.$$

Best proximity point theorems are interestingly a natural generalization of fixed point theorems, as a best proximity point becomes a fixed point if the mapping under consideration is a self-map. In what follows, we set

$$A_0 = \{u \in A : d(u, v) = d(A, B) \text{ for some } v \in B\},$$

$$B_0 = \{v \in B : d(u, v) = d(A, B) \text{ for some } u \in A\}.$$

Motivated by the recent results, we first present the concept of a graphical convex metric space, which generalizes the notion of convex metric spaces in the sense of Takahashi [15] and improves upon the concept of graphical convex metric spaces in the sense of Chen [21]. Furthermore, we introduce the concept of weak enriched G -contraction in this new space, which serves as a generalization of both weak enriched contraction and G -contraction. To explore the best approximation point for enriched-type non-self mappings, we define weak proximal enriched G -contractions of type (I) and type (II). We establish the best approximation point theorem for the mapping T and the average mapping T_λ , considering scenarios of both continuity and discontinuity for T . Furthermore, we present examples to illustrate our theoretical results.

2. Main results

Throughout this paper, we assume that G is a directed, reflexive, and transitive graph with $V(G) = X$. We denote $T_\lambda u = W(u, Tu; \lambda)$ for $\lambda \in [0, 1]$.

Firstly, we define the concept of a graphical convex metric space, which generalizes the classical notion of convex metric spaces and improves the concept of graphical convex metric spaces presented in reference [21, 22].

Definition 2.1. Let (X, d) be a metric space endowed with a graph G . If a mapping $W : V(G) \times V(G) \times [0, 1] \rightarrow V(G)$ satisfies

$$d(z, W(u, v; \lambda)) \leq \lambda d(z, u) + (1 - \lambda)d(z, v), \quad (2.1)$$

for all $z, u, v \in V(G)$ with $(u, v) \in E(G)$ and $\lambda \in [0, 1]$. Then (X, d, W, G) is said to be a graphical convex metric space.

Remark 2.1. Every convex metric space (X, d, W) is a graphical convex metric space and every graphical convex metric space (G, d, W) in the sense of Chen [21] is a graphical convex metric space, where $V(G) = X$ and $E(G) = X \times X$. However, the reverse may not necessarily be true. See the example below.

Example 2.1. Let $X = [1, 2] \cup \{3\}$ and $d(u, v) = |u - v|$ for all $x, y \in X$. It is not difficult to see that there is no convex structure $W : X \times X \times [0, 1] \rightarrow X$ that satisfies (1.1). Let $E(G) = \{(u, v) : u, v \in [1, 2]\}$ and define $W : V(G) \times V(G) \times [0, 1] \rightarrow V(G)$ by

$$W(u, v; \lambda) = \lambda u + (1 - \lambda)v,$$

for all $u, v \in V(G)$ with $(u, v) \in E(G)$ and $\lambda \in [0, 1]$. Clearly, (X, d, W, G) is a graphical convex metric space, and it is not a graphical convex metric space in the sense of Chen [21].

Proposition 2.1. *Let (X, d, W, G) be a graphical convex metric space. For all $u, v \in V(G)$ with $(u, v) \in E(G)$ and $\lambda \in [0, 1]$, we have*

$$d(u, v) = d(u, W(u, v; \lambda)) + d(W(u, v; \lambda), v). \quad (2.2)$$

Proof. Using the triangle inequality and (2.1), we get

$$\begin{aligned} d(u, v) &\leq d(u, W(u, v; \lambda)) + d(W(u, v; \lambda), v) \\ &\leq (1 - \lambda)d(u, v) + \lambda d(u, v) \\ &= d(u, v). \end{aligned}$$

Thus, (2.2) holds. \square

Proposition 2.2. *Let (X, d, W, G) be a graphical convex metric space. For all $u, v \in V(G)$ with $(u, v) \in E(G)$ and $\lambda \in [0, 1]$, we have*

$$d(u, W(u, v; \lambda)) = (1 - \lambda)d(u, v), \quad d(W(u, v; \lambda), v) = \lambda d(u, v). \quad (2.3)$$

Proof. By (2.1) and (2.2), we get

$$\begin{aligned} d(u, v) &= d(u, W(u, v; \lambda)) + d(W(u, v; \lambda), v) \\ &\leq (1 - \lambda)d(u, v) + \lambda d(u, v) \end{aligned}$$

$$= d(u, v).$$

Thus, (2.3) holds. \square

The following proposition is obviously valid.

Proposition 2.3. *Let (X, d, W, G) be a graphical convex metric space. For all $u, v \in V(G)$ with $(u, v) \in E(G)$ and $\lambda \in [0, 1]$, we have*

$$W(u, u; \lambda) = u, \quad W(u, v; 1) = u, \quad W(u, v; 0) = v.$$

Let $u_0 \in V(G)$ be the initial value of a sequence $\{u_n\}$, and let $T : V(G) \rightarrow V(G)$ be a mapping. We say that $\{u_n\}$ is a T -Krasnoselskij sequence if $u_{n+1} = W(u_n, Tu_n; \lambda)$, where $\lambda \in [0, 1]$.

Definition 2.2. Let (X, d, W, G) be a graphical convex metric space. The set $E(G)$ is said to be convex if for any $u_1, v_1, u_2, v_2 \in V(G)$ with $(u_1, v_1) \in E(G)$ and $(u_2, v_2) \in E(G)$, and for all $\lambda \in [0, 1]$, we have $(W(u_1, u_2; \lambda), W(v_1, v_2; \lambda)) \in E(G)$.

Example 2.2. Let $X = \mathbb{R}$. Define $d(u, v) = |u - v|$ and $W(u, v; \lambda) = \lambda u + (1 - \lambda)v$ for all $u, v \in X$ and $\lambda \in [0, 1]$. Consider the graph $E(G) = \{(u, v) \in X \times X : u \leq v\}$. It is clear that if $u_1 \leq v_1$ and $u_2 \leq v_2$, then $W(u_1, u_2; \lambda) \leq W(v_1, v_2; \lambda)$ for any $\lambda \in [0, 1]$. Hence, $E(G)$ is convex in $X \times X$.

More examples of $E(G)$ being convex can be found in references [23, 24]. Next, we will establish some properties of the T -Krasnoselskij iteration processes through convexity.

Proposition 2.4. *Let (X, d, W, G) be a graphical convex metric space. Choose $u_0 \in V(G)$ such that $(u_0, Tu_0) \in E(G)$ and let the sequence $\{u_n\}$ be a T -Krasnoselskij sequence. Suppose that*

- (1) *the mapping $T : V(G) \rightarrow V(G)$ is edge-preserving, that is, $(Tu, Tv) \in E(G)$ for all $(u, v) \in E(G)$;*
- (2) *$E(G)$ is convex.*

Then $(u_n, Tu_n) \in E(G)$ and $(u_n, u_{n+p}) \in E(G)$ for any $n, p \in \mathbb{N}$.

Proof. By the convexity of $E(G)$ and $(u_0, u_0) \in E(G)$, $(u_0, Tu_0) \in E(G)$, we get $(u_0, W(u_0, Tu_0; \lambda)) \in E(G)$, that is, $(u_0, u_1) \in E(G)$. Since T is edge-preserving, we get $(Tu_0, Tu_1) \in E(G)$. By the transitive property of G , we get $(u_0, Tu_1) \in E(G)$. Combining this with $(Tu_0, Tu_1) \in E(G)$ and the convexity of $E(G)$, we get $(u_1, Tu_1) \in E(G)$. Using a similar argument, we can conclude that $(u_n, u_{n+1}) \in E(G)$ and $(u_n, Tu_n) \in E(G)$. By the transitive property of G , we also get $(u_n, u_{n+p}) \in E(G)$, for all $p \in \mathbb{N}$ (for more details see Figure 1). \square

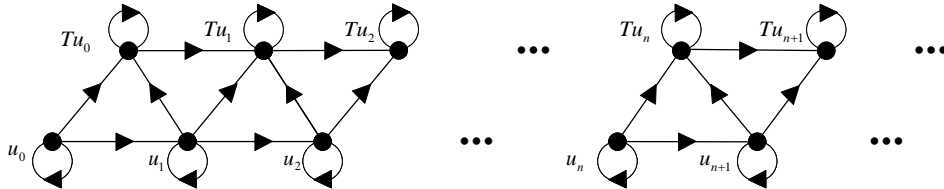


Figure 1. The T -Krasnoselskij sequence associated with Proposition 2.4

Remark 2.2. If T is edge-preserving and $E(G)$ is convex, then T_λ is also edge-preserving.

The following definition is that of weak enriched contraction, which generalizes enriched contraction and weak contraction.

Definition 2.3. Let (X, d, W) be a convex metric space. A mapping $T : X \rightarrow X$ is said to be a weak enriched contraction if there exists $\lambda \in [0, 1)$ such that for all $u, v \in X$, the following inequality holds:

$$d(T_\lambda u, T_\lambda v) \leq d(u, v) - \eta(d(u, v)),$$

where $\eta : [0, \infty) \rightarrow [0, \infty)$ is continuous and nondecreasing function satisfying $\eta(t) = 0$ if and only if $t = 0$.

We also present the definitions of weak enriched G -contraction, which generalize weak enriched contraction and G -contraction, as follows:

Definition 2.4. Let (X, d, W, G) be a graphical convex metric space. A mapping T is said to be a weak enriched G -contraction if the following conditions are satisfied:

- (1) T_λ is edge-preserving, meaning that if $(u, v) \in E(G)$, then $(T_\lambda u, T_\lambda v) \in E(G)$ for all $u, v \in V(G)$;
- (2) there exists $\lambda \in [0, 1)$ such that for all $u, v \in V(G)$ with $(u, v) \in E(G)$, the following inequality holds:

$$d(T_\lambda u, T_\lambda v) \leq d(u, v) - \eta(d(u, v)),$$

where $\eta : [0, \infty) \rightarrow [0, \infty)$ is continuous and nondecreasing function satisfying $\eta(t) = 0$ if and only if $t = 0$.

Example 2.3. Any weak enriched contraction mapping is a weak enriched G_0 -contraction, where the graph G_0 is defined by $V(G_0) = X$ and $E(G_0) = X \times X$.

Weak enriched G -contraction is not necessarily a weak enriched contraction.

Example 2.4. Let $X = [0, 2]$ equipped with the usual metric d . Assessing the graph G with $V(G) = X$ and $E(G) = \{(u, u) : 0 \leq u \leq 2\} \cup \{(\frac{1}{2}, u) : 0 \leq u \leq 1\} \cup \{(\frac{3}{2}, u) : 1 < u < 2\}$. Define $W(u, v; \lambda) = \lambda u + (1 - \lambda)v$ for all $u, v \in V(G)$ with $(u, v) \in E(G)$ and $\lambda \in [0, 1)$. It is clear that (X, d, W, G) is a graphical convex metric space. Define the mapping $T : X \rightarrow X$ by

$$Tu = \begin{cases} 1 - u & 0 \leq u \leq 1 \\ 3 - u & 1 < u \leq 2, \end{cases}$$

take $\lambda = \frac{1}{2}$, then

$$T_{\frac{1}{2}}u = \begin{cases} \frac{1}{2} & 0 \leq u \leq 1 \\ \frac{3}{2} & 1 < u \leq 2. \end{cases}$$

It is clear that if $(u, v) \in E(G)$, then $(Tu, Tv) \in E(G)$ (and also $(T_{\frac{1}{2}}u, T_{\frac{1}{2}}v) \in E(G)$). Note that $d(T_{\frac{1}{2}}u, T_{\frac{1}{2}}v) = 0$ for all $u, v \in V(G)$ with $(u, v) \in E(G)$, thus $d(T_{\frac{1}{2}}u, T_{\frac{1}{2}}v) \leq kd(u, v)$ for any $k \in [0, 1)$, that is, T is a weak enriched

G -contraction with $\eta(t) = kt$ for any $t \geq 0$. However, T is not weak enriched contraction, as let $u = \frac{2}{3}, v = \frac{4}{3}$, we have

$$d(W(\frac{2}{3}, T\frac{2}{3}; \lambda), W(\frac{4}{3}, T\frac{4}{3}; \lambda)) = \frac{2}{3} |2 - \lambda| > \frac{2}{3} = d(\frac{2}{3}, \frac{4}{3}).$$

Clearly, we have the following relations.

$$\begin{aligned} \text{Banach contraction} &\Rightarrow \text{enriched contraction} \Rightarrow \text{weak enriched contraction} \\ &\Rightarrow \text{weak enriched } G\text{-contraction} \end{aligned}$$

Motivated by the ideas of Basha [25,26], we introduce the concept of a G -proximal mapping in a graphical convex metric space as follows.

Definition 2.5. Let (X, d, W, G) be a graphical convex metric space and A and B are two non-empty sets of $V(G)$. A mapping $T : A \rightarrow B$ is said to be G -proximal if T satisfies

$$\left. \begin{aligned} (v_1, v_2) &\in E(G) \\ d(u_1, Tv_1) &= d(A, B) \\ d(u_2, Tv_2) &= d(A, B) \end{aligned} \right\} \Rightarrow (u_1, u_2) \in E(G)$$

for all $u_1, u_2, v_1, v_2 \in A$.

Now, we will provide the definitions of weak proximal enriched G -contraction of type (I) and type (II).

Definition 2.6. Let (X, d, W, G) be a graphical convex metric space, and let A and B be two nonempty subsets of $V(X)$. A mapping $T : A \rightarrow B$ is said to be a weak proximal enriched G -contraction of type (I) if , there exists $\lambda \in [0, 1)$ such that

$$\left. \begin{aligned} (v_1, v_2) &\in E(G) \\ d(u_1, Tv_1) &= d(A, B) \\ d(u_2, Tv_2) &= d(A, B) \end{aligned} \right\} \Rightarrow d(W(v_1, u_1; \lambda), W(v_2, u_2; \lambda)) \leq d(v_1, v_2,) - \eta(d(v_1, v_2,)),$$

for all $u_1, u_2, v_1, v_2 \in A$, where $\eta : [0, \infty) \rightarrow [0, \infty)$ is continuous and nondecreasing satisfying $\eta(t) = 0$ if and only if $t = 0$.

Definition 2.7. Let (X, d, W, G) be a graphical convex metric space, and let A and B be two nonempty subsets of $V(X)$. A mapping $T : A \rightarrow B$ is said to be a weak proximal enriched G -contraction of type (II) if , there exists $\lambda \in [0, 1)$ such that

$$\left. \begin{aligned} (v_1, v_2) &\in E(G) \\ d(u_1, W(v_1, Tv_1; \lambda)) &= d(A, B) \\ d(u_2, W(v_2, Tv_2; \lambda)) &= d(A, B) \end{aligned} \right\} \Rightarrow d(u_1, u_2) \leq d(v_1, v_2,) - \eta(d(v_1, v_2,)),$$

for all $u_1, u_2, v_1, v_2 \in A$, where $\eta : [0, \infty) \rightarrow [0, \infty)$ is continuous and nondecreasing satisfying $\eta(t) = 0$ if and only if $t = 0$.

Remark 2.3. (1) In Definition 2.6, if T is G -proximal and $E(G)$ is convex, we obtain the definition of weak enriched G -contraction when $A = B$.

(2) In Definition 2.7, if T_λ is G -proximal, then we obtain the definition of weak enriched G -contraction when $A = B$.

Now, we present our first main result.

Theorem 2.1. *Let (X, d, W, G) be a complete graphical convex metric space and $E(G)$ is convex. Let A and B be two nonempty closed subsets of $V(X)$ such that A_0 is convex. Assume that $T : A \rightarrow B$ is a continuous weak proximal enriched G -contraction of type (I), if it satisfies the following conditions:*

- (1) T is G -proximal with $T(A_0) \subseteq B_0$;
- (2) there exist elements $u_0, z_0 \in A_0$ such that $(u_0, z_0) \in E(G)$ and $d(z_0, Tu_0) = d(A, B)$.

Then T has a best proximity point in A . Furthermore, if for any two best proximity points $u^, u^{**} \in A$, we have $(u^*, u^{**}) \in E(G)$, then T has a unique best proximity point in A .*

Proof. Let u_0 and z_0 in A_0 be such that $(u_0, z_0) \in E(G)$ and $d(z_0, Tu_0) = d(A, B)$. Let $u_1 = W(u_0, z_0; \lambda)$, since A_0 is convex, then $u_1 \in A_0$. From the fact that $T(A_0) \subseteq B_0$, there exists $z_1 \in A_0$ such that $d(z_1, Tu_1) = d(A, B)$. From $(u_0, u_0) \in E(G)$, $(u_0, z_0) \in E(G)$ and the convexity of $E(G)$, we have $(u_0, u_1) \in E(G)$. Since T is G -proximal, we get $(z_0, z_1) \in E(G)$. By using the transitive property of G , we have $(u_0, z_1) \in E(G)$, by combining this with $(z_0, z_1) \in E(G)$ and the convexity of $E(G)$, we obtain that $(u_1, z_1) \in E(G)$. Using a similar argument, we can obtain two sequences $\{u_n\}$ and $\{z_n\}$ in A_0 such that $d(z_n, Tu_n) = d(A, B)$ with $(u_n, z_n) \in E(G)$, $(u_n, u_{n+1}) \in E(G)$ and $u_{n+1} = W(u_n, z_n; \lambda)$ for any $n \in \mathbb{N}$. Moreover, by using the transitive property of G , we can deduce that $(u_n, u_{n+p}) \in E(G)$ for any $p \in \mathbb{N}$ (for more details see Figure 2). If there exists $n_0 \in \mathbb{N}$ such that $u_{n_0} = u_{n_0+1}$, we have

$$d(u_{n_0}, z_{n_0}) = d(u_{n_0+1}, z_{n_0}) \leq (1 - \lambda)d(u_{n_0}, z_{n_0})$$

which implies $d(u_{n_0}, z_{n_0}) = 0$, it follows that

$$d(A, B) \leq d(u_{n_0}, Tu_{n_0}) \leq d(u_{n_0}, z_{n_0}) + d(z_{n_0}, Tu_{n_0}) = d(A, B),$$

thus $d(u_{n_0}, Tu_{n_0}) = d(A, B)$, that is, u_{n_0} is a best proximity point of T . Hence, we suppose that $d(u_n, u_{n+1}) > 0$ for all $n \in \mathbb{N}$. Since T is weak proximal enriched G -contraction of type (I), we have

$$d(W(u_{n-1}, z_{n-1}; \lambda), W(u_n, z_n; \lambda)) \leq d(u_{n-1}, u_n) - \eta(d(u_{n-1}, u_n)),$$

it follows that $d(u_n, u_{n+1}) \leq d(u_{n-1}, u_n) - \eta(d(u_{n-1}, u_n)) < d(u_{n-1}, u_n)$, this gives that $\{d(u_n, u_{n+1})\}$ is a decreasing sequence of nonnegative real numbers. Assume that $\lim_{n \rightarrow \infty} d(u_n, u_{n+1}) = t \geq 0$. If $t > 0$, then $\eta(t) > 0$. For any $n \in \mathbb{N}$, we have

$$t = \lim_{n \rightarrow \infty} d(u_n, u_{n+1}) \leq \lim_{n \rightarrow \infty} d(u_{n-1}, u_n) - \eta(\lim_{n \rightarrow \infty} d(u_{n-1}, u_n)) = t - \eta(t),$$

a contradiction. Hence, $\lim_{n \rightarrow \infty} d(u_n, u_{n+1}) = 0$. Now, we show that $\{u_n\}$ is a Cauchy sequence. On the contrary, suppose that $\{u_n\}$ is not a Cauchy sequence. Then there exist $\varepsilon > 0$ and two sequences $\{m_k\}, \{n_k\}$ of positive integers such that

$$n_k > m_k > k, \quad d(u_{m_k}, u_{n_k}) \geq \varepsilon \quad \text{and} \quad d(u_{m_k}, u_{n_k-1}) < \varepsilon.$$

We have

$$\varepsilon \leq d(u_{m_k}, u_{n_k}) \leq d(u_{m_k}, u_{n_k-1}) + d(u_{n_k-1}, u_{n_k}),$$

let $k \rightarrow \infty$, we deduce that $\lim_{k \rightarrow \infty} d(u_{m_k}, u_{n_k}) = \varepsilon$. Further, from

$$d(u_{m_k}, u_{n_k}) \leq d(u_{m_k}, u_{m_k+1}) + d(u_{m_k+1}, u_{n_k+1}) + d(u_{n_k+1}, u_{n_k})$$

and

$$d(u_{m_k+1}, u_{n_k+1}) \leq d(u_{m_k+1}, u_{m_k}) + d(u_{m_k}, u_{n_k}) + d(u_{n_k}, u_{n_k+1}),$$

we get $\lim_{k \rightarrow \infty} d(u_{m_k+1}, u_{n_k+1}) = \varepsilon$. Since T is weak proximal enriched G -contraction of type (I) with $(u_{m_k}, u_{n_k}) \in E(G)$, it follows that

$$d(u_{m_k+1}, u_{n_k+1}) \leq d(u_{m_k}, u_{n_k}) - \eta(d(u_{m_k}, u_{n_k})),$$

by letting $k \rightarrow \infty$, we get $\varepsilon \leq \varepsilon - \eta(\varepsilon)$ which yields $\eta(\varepsilon) = 0$, a contradiction. Therefore, the sequence $\{u_n\}$ is Cauchy sequence in A . Since A is a closed subset of $V(X)$, there exists a $u^* \in A$ such that $u_n \rightarrow u^*$. Further, using the triangle inequality, we get

$$d(z_n, u_n) \leq d(z_n, u_{n+1}) + d(u_{n+1}, u_n) \leq \lambda d(z_n, u_n) + d(u_{n+1}, u_n),$$

which implies $\lim_{n \rightarrow \infty} d(z_n, u_n) = 0$, thus $z_n \rightarrow u^*$. Since T is continuous, we have $Tu_n \rightarrow Tu$. By the continuity of the metric function d , we have $d(u_n, Tu_n) \rightarrow d(u^*, Tu^*)$. Then

$$d(A, B) \leq d(u_n, Tu_n) \leq d(u_n, z_n) + d(z_n, Tu_n) = d(u_n, z_n) + d(A, B),$$

Let $n \rightarrow \infty$, we obtain that $d(u^*, Tu^*) = d(A, B)$, that is u^* is a best proximity point of T . Let us suppose that T has another best proximity point u^{**} in A with $(u^*, u^{**}) \in E(G)$, that is, $d(u^{**}, Tu^{**}) = d(A, B)$. Since T is a weak proximal enriched G -contraction of type (I) , we have

$$d(u^*, u^{**}) = d(W(u^*, u^*; \lambda), W(u^{**}, u^{**}; \lambda)) \leq d(u^*, u^{**}) - \eta(d(u^*, u^{**})),$$

which implies $u^* = u^{**}$. This complete the proof. \square

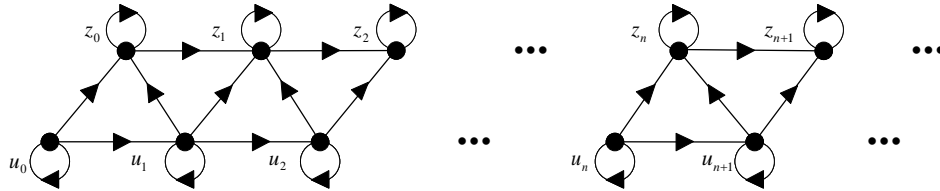


Figure 2. The graph of $\{u_n\}$ and $\{z_n\}$ in Theorem 2.1

In order to remove the continuity assumption, we need the following condition.

Definition 2.8. [20] For any sequence $\{u_n\}$ in X , if $u_n \rightarrow u$ and $(u_n, u_{n+1}) \in E(G)$ for all $n \in \mathbb{N}$, then there is a subsequence $\{u_{n_k}\}$ of $\{u_n\}$, such that $(u_{n_k}, u) \in E(G)$ for all $k \in \mathbb{N}$. We say graph G satisfy the property (P) .

Remark 2.4. If $u_n \rightarrow u$ and $(u_n, u_{n+1}) \in E(G)$. Suppose that G has the property (P) , by the transitive property of G , we have $(u_n, u) \in E(G)$ for all $n \in \mathbb{N}$.

Definition 2.9. [25, 26] Let (X, d) be a metric space, and let A and B be two nonempty subsets of X . A is said to be approximatively compact with respect to B if any sequence $\{u_n\}$ in A satisfying the condition that $d(u_n, v) \rightarrow d(A, v)$ for some $v \in B$ has a convergent subsequence.

Theorem 2.2. Let (X, d, W, G) be a complete graphical convex metric space. Suppose that G has the property (P) and $E(G)$ is convex. Let A and B be two nonempty closed subsets of $V(X)$ such that A_0 is convex and B is approximatively compact with respect to A . Assume that $T : A \rightarrow B$ is a weak proximal enriched G -contraction of type (I) , if it satisfies the following conditions:

- (1) T is G -proximal with $T(A_0) \subseteq B_0$;
- (2) there exist elements $u_0, z_0 \in A_0$ such that $(u_0, z_0) \in E(G)$ and $d(z_0, Tu_0) = d(A, B)$.

Then T has a best proximity point in A . Furthermore, if for any two best proximity points $u^*, u^{**} \in A$, we have $(u^*, u^{**}) \in E(G)$, then T has a unique best proximity point in A .

Proof. Proceeding as in the proof of Theorem 2.1, it is guaranteed that there are two sequences $\{u_n\}$ and $\{z_n\}$ in A_0 such that $d(z_n, Tu_n) = d(A, B)$ with $(u_n, z_n) \in E(G)$, $(u_n, u_{n+1}) \in E(G)$ and $u_{n+1} = W(u_n, z_n; \lambda)$ for any $n \in \mathbb{N}$. By using similar arguments as in the proof of Theorem 2.1, we can conclude that $\{u_n\}$ is Cauchy sequence in A and $\lim_{n \rightarrow \infty} d(z_n, u_n) = 0$. Due to the fact that A is a closed subset of $V(X)$, there exists an element $u^* \in A$ such that $u_n \rightarrow u^*$. By property (P) , we conclude that $(u_n, u^*) \in E(G)$ for all $n \in \mathbb{N}$. Further, using the triangle inequality, we get

$$d(z_n, u^*) \leq d(z_n, u_n) + d(u_n, u^*),$$

which implies $z_n \rightarrow u^*$. Besides, we have

$$\begin{aligned} d(u^*, B) &\leq d(u^*, Tu_n) \\ &\leq d(u^*, z_n) + d(z_n, Tu_n) \\ &= d(u^*, z_n) + d(A, B) \\ &\leq d(u^*, z_n) + d(u^*, B), \end{aligned}$$

let $n \rightarrow \infty$, we have $\lim_{n \rightarrow \infty} d(u^*, Tu_n) = d(u^*, B)$. Since B is approximatively compact with respect to A , it follows that the sequence $\{Tu_n\}$ has a subsequence $\{Tu_{n_k}\}$ converging v in B . Then we obtain

$$d(u^*, v) = \lim_{n \rightarrow \infty} d(u_n, Tu_n) = d(A, B),$$

which implies that $u^* \in A_0$. Again, since $T(A_0) \subseteq B_0$, there exists an element $z \in A_0$ such that $d(z, Tu^*) = d(A, B)$, since T is a weak proximal enriched G -contraction of type (I) , it follows that

$$d(W(u_n, z_n; \lambda), W(u^*, z; \lambda)) \leq d(u_n, u^*) - \eta(d(u_n, u^*)).$$

We obtain

$$\begin{aligned} d(u^*, W(u^*, z; \lambda)) &\leq d(u^*, u_{n+1}) + d(u_{n+1}, W(u^*, z; \lambda)) \\ &= d(u^*, u_{n+1}) + d(W(u_n, z_n; \lambda), W(u^*, z; \lambda)) \\ &\leq d(u^*, u_{n+1}) + d(u_n, x^*) - \eta(d(u_n, u^*)), \end{aligned}$$

let $n \rightarrow \infty$, we have $d(u^*, W(u^*, z; \lambda)) = 0$, which implies that $u^* = z$. Therefore $d(u^*, Tu^*) = d(A, B)$ and u^* is a best proximity point of T . Let us suppose that T has another best proximity point u^{**} in A with $(u^*, u^{**}) \in E(G)$, that is, $d(u^{**}, Tu^{**}) = d(A, B)$. Since T is a weak proximal enriched G -contraction of type (I) , we have

$$d(u^*, u^{**}) = d(W(u^*, u^*; \lambda), W(u^{**}, u^{**}; \lambda)) \leq d(u^{**}, u^*) - \eta(d(u^*, u^{**})),$$

which implies $u^* = u^{**}$. This complete the proof. \square

Next, we will give an example to support Theorem 2.2.

Example 2.5. Let $X = \mathbb{R}^2$ and define $d(u, v) = |u_1 - u_3| + |u_2 - u_4|$ for all $u = (u_1, u_2), v = (u_3, u_4) \in X$. Consider the graph G with $V(G) = X$ and $E(G) = \{((u_1, u_2), (u_3, u_4)) : u_1 \leq u_3, u_2 \leq u_4\}$. Define $W((u_1, u_2), (u_3, u_4); \lambda) = (\lambda u_1 + (1 - \lambda)u_3, \lambda u_2 + (1 - \lambda)u_4)$ for all $(u_1, u_2), (u_3, u_4) \in V(G)$ with $((u_1, u_2), (u_3, u_4)) \in E(G)$ and $\lambda \in (0, 1)$. Clear, (X, d, W, G) is a complete graphical convex metric space. It is easy to show that G is reflexive and transitive, and $E(G)$ is convex. Let $A = \{(0, u_1) : 0 \leq u_1 \leq 1\}$ and $B = \{(1, u_2) : 0 \leq u_2 \leq 1\}$. Then A and B are nonempty closed subsets of $V(G)$ and $A = A_0, B = B_0$, then B is approximatively compact with respect to A . Let $T : A \rightarrow B$ defined by $T(0, u) = (1, \frac{u}{2})$. Note that $d(A, B) = 1$ and $T(A_0) \subseteq B_0$. Assume that e_1, e_2, e_3, e_4 be elements in A such that $d(e_1, Te_2) = d(A, B), d(e_3, Te_4) = d(A, B)$. Take $e_2 = (0, r_1), e_4 = (0, r_2)$ and $r_1 \leq r_2$. Then $e_1 = (0, \frac{r_1}{2})$ and $e_3 = (0, \frac{r_2}{2})$. It is easy to show that $(e_2, e_4) \in E(G)$ and $(e_1, e_3) \in E(G)$. Hence T is G -proximal. Moreover,

$$\begin{aligned} d(W(e_1, e_2; \lambda), W(e_3, e_4; \lambda)) &= d((0, \lambda r_1 + (1 - \lambda)\frac{r_1}{2}), (0, \lambda r_2 + (1 - \lambda)\frac{r_2}{2})) \\ &= \left| \lambda(r_1 - r_2) + (1 - \lambda)\frac{r_1 - r_2}{2} \right| \\ &= \frac{\lambda + 1}{2} |r_1 - r_2| \\ &= \frac{\lambda + 1}{2} (|0 - 0| + |r_1 - r_2|) \\ &= \frac{\lambda + 1}{2} d(e_2, e_4). \end{aligned}$$

Since $\lambda < 1$, thus T is a weak proximal enriched G -contraction of type (I) . Therefore, all hypotheses of Theorem 2.2 is satisfied, we obtain that T has a unique best proximity point $(0, 0)$.

We present the convergence plots of the sequences $\{u_n\}$ and $\{z_n\}$ for the initial value $u_0 = (0, 1)$ in Figure 3.

Remark 2.5. Let T defined as in Example 2.5 and the averaged mapping defined by $T_\lambda u = W(u, Tu; \lambda)$ for all $u \in V(G)$ and $\lambda \in (0, 1)$. It is worth noting that the best proximity point of T is not a best proximity point of T_λ . Indeed, $T_\lambda(0, 0) = W((0, 0), (1, 0); \lambda) = (0, (1 - \lambda))$, then $d((0, 0), T_\lambda(0, 0)) = 1 - \lambda < d(A, B) = 1$.

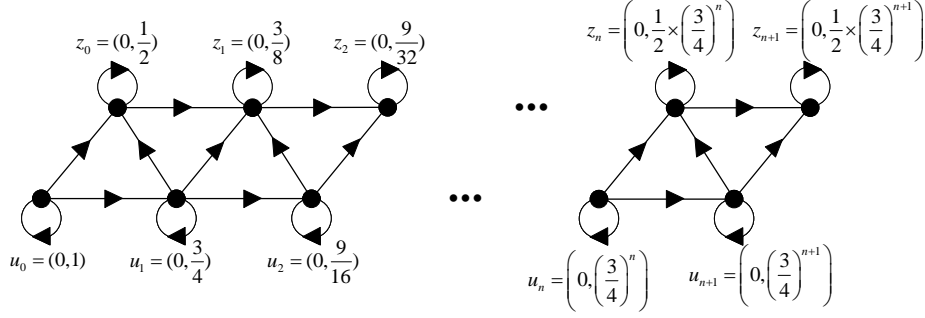


Figure 3. Graph associated with Example 2.5

Theorem 2.3. Let (X, d, W, G) be a complete graphical convex metric space and G has the property (P) . Let A and B be two nonempty closed subsets of $V(X)$ and B is approximately compact with respect to A . Assume that $T : A \rightarrow B$ is a weak proximal enriched G -contraction of type (II) , if it satisfies the following conditions:

- (1) T_λ is G -proximal with $T_\lambda(A_0) \subseteq B_0$;
- (2) there exist elements $u_0, u_1 \in A_0$ such that $(u_0, u_1) \in E(G)$ and $d(u_1, T_\lambda u_0) = d(A, B)$.

Then T_λ has a best proximity point in A . Furthermore, if for any two best proximity points $u^*, u^{**} \in A$, we have $(u^*, u^{**}) \in E(G)$, then T_λ has a unique best proximity point in A .

Proof. Let u_0 and u_1 in A_0 be such that $(u_0, u_1) \in E(G)$ and $d(u_1, T_\lambda u_0) = d(A, B)$. In view of the fact that $T_\lambda(A_0) \subseteq B_0$, there exists $u_2 \in A_0$ such that $d(u_2, T u_1) = d(A, B)$. Since T_λ is G -proximal, we get $(u_1, u_2) \in E(G)$. Continuing this process, we can obtain a sequence $\{u_n\}$ in A_0 such that $d(u_{n+1}, T_\lambda u_n) = d(A, B)$ and $(u_n, u_{n+1}) \in E(G)$ for any $n \in \mathbb{N}$. By using the transitive property of G , we can deduce that $(u_n, u_{n+p}) \in E(G)$ for any $p \in \mathbb{N}$ (for more details see Figure 4). If there exists $n_0 \in \mathbb{N}$ such that $u_{n_0} = u_{n_0+1}$, we have

$$d(u_{n_0}, T_\lambda u_{n_0}) = d(u_{n_0+1}, T_\lambda u_{n_0}) = d(A, B)$$

which implies u_{n_0} is a best proximity point of T_λ . Hence, we suppose that $d(u_n, u_{n+1}) > 0$ for all $n \in \mathbb{N}$. Since T is a weak proximal enriched G -contraction of type (II) , it follows that

$$d(u_n, u_{n+1}) \leq d(u_{n-1}, u_n) - \eta(d(u_{n-1}, u_n)).$$

By using similar arguments as in the proof of Theorem 2.1, we can conclude that $\{u_n\}$ is Cauchy sequence in A . Due to the fact that A is a closed subset of $V(G)$, there exists a $u^* \in A$ such that $u_n \rightarrow u^*$. By property (P) , we conclude that $(u_n, u^*) \in E(G)$ for all $n \in \mathbb{N}$. Besides, we have

$$\begin{aligned} d(u^*, B) &\leq d(u^*, T_\lambda u_n) \\ &\leq d(u^*, u_{n+1}) + d(u_{n+1}, T_\lambda u_n) \\ &= d(u^*, u_{n+1}) + d(A, B) \\ &\leq d(u^*, u_{n+1}) + d(u^*, B). \end{aligned}$$

Let $n \rightarrow \infty$, we have $\lim_{n \rightarrow \infty} d(u^*, T_\lambda u_n) = d(u^*, B)$. Since B is approximatively compact with respect to A , it follows that the sequence $\{T_\lambda u_n\}$ has a subsequence $\{T_\lambda u_{n_k}\}$ converging v in B . So we obtain

$$d(u^*, v) = \lim_{n \rightarrow \infty} d(u_n, T_\lambda u_n) = d(A, B),$$

which implies that $u^* \in A_0$. Again, since $T_\lambda(A_0) \subseteq B_0$, there exists an element $z \in A_0$ such that $d(z, T_\lambda u^*) = d(A, B)$, since T is a weak proximal enriched G -contraction of type (II), it follows that

$$d(u_{n+1}, z) \leq d(u_n, u^*) - \eta(d(u_n, u^*)).$$

Let $n \rightarrow \infty$, we have $d(u^*, z) = 0$ which implies that $u^* = z$. Therefore $d(u^*, T_\lambda u^*) = d(A, B)$ and u^* is a best proximity point of T_λ . Let us suppose that T_λ has another best proximity point u^{**} in A with $(u^*, u^{**}) \in E(G)$, that is, $d(u^{**}, T_\lambda u^{**}) = d(A, B)$. Since T_λ is a weak proximal enriched G -contraction of type (II), we have

$$d(u^*, u^{**}) \leq d(u^*, u^{**}) - \eta(d(u^*, u^{**})),$$

which implies $u^* = u^{**}$. This complete the proof. \square



Figure 4. The graph of $\{u_n\}$ in Theorem 2.3

Example 2.6. Let $X = \mathbb{R}^2$ and define $d(u, v) = |u_1 - u_3| + |u_2 - u_4|$ for all $u = (u_1, u_2), v = (u_3, u_4) \in X$. Consider the graph G with $V(G) = X$ and $E(G) = \{((u_1, u_2), (u_3, u_4)) : u_1 \leq u_3, u_2 \leq u_4\}$. Define $W((u_1, u_2), (u_3, u_4); \lambda) = (\lambda u_1 + (1 - \lambda)u_3, \lambda u_2 + (1 - \lambda)u_4)$ for any $(u_1, u_2), (u_3, u_4) \in V(G)$ with $((u_1, u_2), (u_3, u_4)) \in E(G)$ and $\lambda \in (0, 1)$. Clear, (X, d, W, G) is a complete graphical convex metric space. Let $A = \{(0, u) : 0 \leq u \leq 1\}, B = \{(u, v) : 1 \leq u \leq 3, 0 \leq v \leq 1\}$. Then A and B are nonempty closed subsets of $V(G)$ and $A = A_0, B = B_0$, then B is approximatively compact with respect to A . Define the mapping $T : A \rightarrow B$ by $T(0, u) = T(3, 1 - u)$ for $u \in [0, 1]$. For $\lambda = \frac{2}{3}$, we have $T_{\frac{2}{3}}(0, u) = W((0, u), (3, 1 - u); \frac{2}{3}) = (1, \frac{1}{3}u + \frac{1}{3})$. Note that $d(A, B) = 1$ and $T_{\frac{2}{3}}(A_0) \subseteq B_0$. It is easy to show that G is reflexive and transitive. Assume that e_1, e_2, e_3, e_4 be elements in A such that $d(e_1, T_{\frac{2}{3}}e_2) = d(A, B), d(e_3, T_{\frac{2}{3}}e_4) = d(A, B)$. Take $e_2 = (0, r_1), e_4 = (0, r_2)$ and $r_1 \leq r_2$. Then $e_1 = (0, \frac{1}{3}r_1 + \frac{1}{3})$ and $e_3 = (0, \frac{1}{3}r_2 + \frac{1}{3})$. It is clear hat $(e_2, e_4) \in E(G)$ and $(e_1, e_3) \in E(G)$. Hence T_λ is G -proximal. Moreover,

$$\begin{aligned} d(e_1, e_3) &= d((0, \frac{1}{3}r_1 + \frac{1}{3}), (0, \frac{1}{3}r_2 + \frac{1}{3})) \\ &= \frac{1}{3} |r_1 - r_2| \\ &= \frac{1}{3} (|0 - 0| + |r_1 - r_2|) \end{aligned}$$

$$= \frac{1}{3}d(e_2, e_4),$$

thus T is a weak proximal enriched G -contraction of type (II) . Therefore, all hypotheses of Theorem 2.3 is satisfied, we obtain that T has a unique best proximity point $(0, \frac{1}{2})$.

We present the convergence plot of the sequences $\{u_n\}$ for the initial value $u_0 = (0, 1)$ in Figure 5.

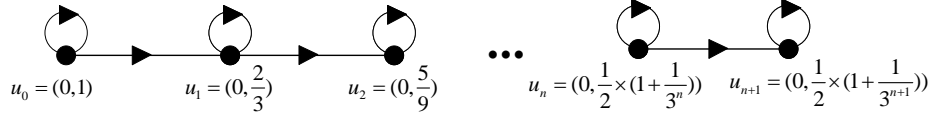


Figure 5. Graph associated with Example 2.6

Taking $A = B$ in Theorem 2.1, we obtain the following fixed point theorem.

Corollary 2.1. *Let (X, d, W, G) be a complete graphical convex metric space and $E(G)$ is convex. Let $T : V(X) \rightarrow V(X)$ be a continuous mapping that satisfies the following conditions:*

- (1) T is edge-preserving;
- (2) there exists $\lambda \in [0, 1)$ such that for all $u, v \in V(G)$ with $(u, v) \in E(G)$, the following inequality holds:

$$d(T_\lambda u, T_\lambda v) \leq d(u, v) - \eta(d(u, v)),$$

where $\eta : [0, \infty) \rightarrow [0, \infty)$ is continuous and nondecreasing function satisfying $\eta(t) = 0$ if and only if $t = 0$. Then T has a fixed point. Furthermore, if for any two fixed points $u^*, u^{**} \in X$, we have $(u^*, u^{**}) \in E(G)$, then T has a unique fixed point.

Taking $A = B$ in Theorem 2.2, we obtain the following fixed point theorem.

Corollary 2.2. *Let (X, d, W, G) be a complete graphical convex metric space. Assume that G has the property (P) and $E(G)$ is convex. Let $T : V(X) \rightarrow V(X)$ be a mapping that satisfies the following conditions:*

- (1) T is edge-preserving;
- (2) there exists $\lambda \in [0, 1)$ such that for all $u, v \in V(G)$ with $(u, v) \in E(G)$, the following inequality holds:

$$d(T_\lambda u, T_\lambda v) \leq d(u, v) - \eta(d(u, v)),$$

where $\eta : [0, \infty) \rightarrow [0, \infty)$ is continuous and nondecreasing function satisfying $\eta(t) = 0$ if and only if $t = 0$. Then T has a fixed point. Furthermore, if for any two fixed points $u^*, u^{**} \in X$, we have $(u^*, u^{**}) \in E(G)$, then T has a unique fixed point.

Taking $A = B$ in Theorem 2.3, we obtain the following fixed point theorem.

Corollary 2.3. *Let (X, d, W, G) be a complete graphical convex metric space and G has the property (P) . Let $T : V(X) \rightarrow V(X)$ be a weak enriched G -contraction, then T has a fixed point. Furthermore, if for any two fixed points $u^*, u^{**} \in X$, we have $(u^*, u^{**}) \in E(G)$, then T has a unique fixed point.*

Note that any weak enriched contraction is a weak enriched G_0 -contraction, we obtain the following fixed point theorem.

Corollary 2.4. *Let (X, d, W) be a complete convex metric space and $T : X \rightarrow X$ be a weak enriched contraction. Then*

- (1) $F(T) = \{u\}$, for some $u \in X$;
- (2) there exists $\lambda \in [0, 1)$ such that the sequence $\{u_n\}_{n=0}^{\infty}$ defined by

$$u_{n+1} = W(u_n, Tu_n; \lambda)$$

converges to u .

Conflict of interest

The authors declare no conflict of interest.

References

- [1] S. Banach, *Sur les opérations dans les ensembles abstraits et leur application aux équations intégrales*, Fund. Math., 1922, 3, 133–181.
- [2] L.B. Ćirić, *A generalization of Banachs contraction principle*, Proc. Am. Math. Soc., 1974, 45, 267–273.
- [3] T. Suzuki, *A new type of fixed point theorem in metric spaces*, Nonlinear Anal.Theor., 2009, 71, 5313–5317.
- [4] D. Wardowski, *Fixed points of a new type of contractive mappings in complete metric spaces*, Fixed Point Theory A., 2012, 2012, 1–6.
- [5] P.D. Proinov, *Fixed point theorems for generalized contractive mappings in metric spaces*, J. Fixed Point Theory Appl., 2020, 22, 21.
- [6] L.L. Chen, C.B. Li, R. Kaczmarek and Y.F. Zhao, *Several fixed point theorems in convex b -metric spaces and applications*, Mathematics, 2020, 8(2), 242.
- [7] L.L. Chen, L. Gao and D.Y. Chen, *Fixed point theorems of mean nonexpansive set-valued mappings in Banach spaces*, J. Fixed Point Theory Appl., 2017, 19, 2129–2143.
- [8] R. Anjum, M. Abbas, and H. I şık. *Completeness problem via fixed point theory*, Complex Anal. Oper. Th., 2023, 17(6),85.
- [9] M. Younis, D. Singh and A. A. N. Abdou, *A fixed point approach for tuning circuit problem in dislocated b -metric spaces*, Math. Meth. Appl. Sci., 2022,45(4), 2234–2253.
- [10] M. Younis, D. Singh, L. L. Chen and M. Metwali, *A study on the solutions of notable engineering models*, Math. Model. Anal., 2022, 27(3), 492–509.
- [11] M. Younis, D. Singh and A. Goyal, *A novel approach of graphical rectangular b -metric spaces with an application to the vibrations of a vertical heavy hanging cable*, J. Fixed Point Theory Appl., 2019, 21, 1–33.
- [12] Ya.I. Alber, S. Guerre-Delabriere, *Principle of weakly contractive maps in Hilbert spaces*, in: New Results in Operator Theory and its Applications, Birkhäuser, Basel, 1997, 98, 7–22.

-
- [13] B.E. Rhoades, Some theorems on weakly contractive maps, *Nonlinear Anal.*, 2001, 47,2683–2693.
- [14] V. Berinde, M. Păcurar, *Approximating fixed points of enriched contractions in Banach spaces*, *J. Fixed Point Theory Appl.*, 2020, 22, 1–10.
- [15] W. Takahashi, *A convexity in metric space and nonexpansive mappings*, I. *Kodai Math. J.*, 1970, 22, 142–149.
- [16] S.H. Khan, M.Abbas, *Common fixed point results with applications in convex metric spaces*, *J. Concr. Appl. Math.*, 2012, 10, 65–76.
- [17] P.R. Agarwal, D O'Regan, D. R. Sahu. *Fixed point theory for Lipschitzian-type mappings with applications*, New York: Springer, 2009, 6.
- [18] V. Berinde, M. Păcurar, *Existence and approximation of fixed points of enriched contractions and enriched φ -Contractions*, *Symmetry* 2021, 13(3), 498.
- [19] R. Espinola, W.A. Kirk, *Fixed point theorems in R -trees with applications to graph theory*, *Topology Appl.*, 2006, 153,1046–1055.
- [20] J. Jachymski, *The contraction principle for mappings on a metric space with a graph*, *Proc. Amer. Math. Soc.*, 2008, 1, 1359–1373.
- [21] L.L. Chen, N. Yang, Y.F. Zhao, Z.H. Ma, *Fixed point theorems for set-valued G -contractions in a graphical convex metric space with applications*, *J. Fixed Point Theory Appl.*, 2020, 22, 1–23.
- [22] L.L. Chen,, Y.Y Jiang and Y.F. Zhao. *Iterative algorithms and fixed point theorems for set-valued G -contractions in graphical convex metric spaces*, *J. Appl. Anal. Comput.*, 2024, 14(6), 3558–3580.
- [23] D. Yambangwai, S. Aunruean, T. Thianwan, *A new modified three-step iteration method for G -nonexpansive mappings in Banach spaces with a graph*, *Numer. Algor*,2019, 20, 1–29.
- [24] T. Thianwan, D. Yambangwai, *Convergence analysis for a new two-step iteration process for G - nonexpansive mappings with directed graphs*, *J. Fixed Point Theory Appl.* 2019, 21(44), 1–16.
- [25] S.S. Basha, Best proximity points: global optimal approximate solutions, *J. Global Optim.*, 49(2011),15–21.
- [26] S.S. Basha, Best proximity point theorems, *J. Approx. Theory*, 2011, 163, 1772–1781.