# EXISTENCE OF THREE POSITIVE SOLUTIONS FOR A CLASS OF RIEMANN-LIOUVILLE FRACTIONAL $Q$-DIFFERENCE EQUATION 

Shugui Kang ${ }^{1, \dagger}$, Huiqin Chen ${ }^{1}$, Luping $\mathrm{Li}^{1}$, Yaqiong Cui ${ }^{1}$ and Shiwang $\mathrm{Ma}^{2}$


#### Abstract

In this paper, we confirm the existence of three positive solutions for a class of Riemann-Liouville fractional $q$-difference equation which satisfies the boundary conditions. We gain several sufficient conditions for the existence of three positive solutions of this boundary value problem by applying the Leggett-Williams fixed point theorem.


Keywords Fractional $q$-integral of the Riemann-Liouville, fractional $q$-derivative of the Riemann-Liouville, fixed point theorem, fractional $q$-difference equation, positive solutions.

MSC(2010) 39A13, 34A08, 34B18.

## 1. Introduction

We consider the following fractional $q$-difference equation with boundary conditions

$$
\begin{align*}
\left(D_{q}^{\alpha} x\right)(t)+f(t, x(t)) & =0,0<q<1,0<t<1,  \tag{1.1}\\
x(0)=D_{q} x(0) & =D_{q} x(1)=0, \tag{1.2}
\end{align*}
$$

where $D_{q}^{\alpha}$ denotes the Riemann-Liouville fractional $q$-derivative of order $\alpha, 2<\alpha<$ $3, f \in C([0,1] \times[0,+\infty)) \rightarrow[0,+\infty)$.

Since the $q$-difference calculus or quantum calculus was founded by Jackson [6,7]. People show great interests in fractional $q$-difference equations. After the fractional $q$-difference calculus was developed by Al-Salam and Agarwal [1, 2], a lot of papers on the fractional $q$-difference equation have been emerged in recent years(consult [4], [8-16], and the other references). The authors employed the existence of solutions or positive solutions for fractional $q$-difference equations by applying the monotone

[^0]iterative method, the upper and lower solutions method and some distinguished fixed-point theories such as Krasnosel'skii and Schauder fixed point theorems, respectively. For example, Ferreira [4] employed the existence of positive solutions for the following nonlinear $q$-fractional boundary value problem
\[

$$
\begin{array}{r}
\left(D_{q}^{\alpha} y\right)(x)=-f(x, y(x)), 0<x<1 \\
y(0)=D_{q} y(0)=0, D_{q} y(1)=\beta \geqslant 0
\end{array}
$$
\]

by applying a fixed point theorem in cones, where $D_{q}^{\alpha}, q, \alpha$ is similar as (1.1)-(1.2).
Li, et al. [10] gained the conditions of the existence of positive solutions for the following nonlinear fractional $q$-difference equation with parameter

$$
\begin{array}{r}
\left(D_{q}^{\alpha} y\right)(x)+\lambda f(y(x)), 0<x<1 \\
y(0)=D_{q} y(0)=D_{q} y(1)=0
\end{array}
$$

depending on the range of parameter $\lambda$ by using the known Guo-Krasnosel'skii fixed point theorem in cones, where $D_{q}^{\alpha}, q, \alpha$ is similar as (1.1)-(1.2).

By using the monotone iterative method and upper and lower solutions method, Zhai and Ren [15] obtained the existence of positive or negative solutions for problem (1.1)-(1.2).

As we all know, few people can solve the existence of three positive solutions for a Riemann-Liouville fractional $q$-difference equation boundary value problem (1.1)-(1.2), by using Leggett-Williams fixed point theorem to study. Inspired by papers $[17,19]$, we confirm the existence of three positive solutions for problem (1.1)-(1.2) by using properties of the Green's function and the Leggett-Williams fixed-point theorem in this paper.

In the followings, we will provide basic definitions and some lemmas in order to prove our main results in Section 2. In Section 3, we establish some results for the existence of three positive solutions to the problem (1.1)-(1.2). In Section 4, we will give some examples to corroborate our results.

## 2. Preliminaries

In order to demonstrate our main results, we show some basic definitions and some lemmas in this piece.

Set $0<q<1$, we define

$$
[s]_{q}=\frac{1-q^{s}}{1-q}, s \in \mathbb{R}
$$

The $q$-analogue of the power function $(s-t)^{n}$ with $n \in \mathbb{N}$ is

$$
(s-t)^{0}=1,(s-t)^{n}=\prod_{k=0}^{n-1}\left(s-t q^{k}\right), n \in \mathbb{N}, s, t \in \mathbb{R}
$$

If $\alpha \in \mathbb{R}$, then

$$
(s-t)^{\alpha}=s^{\alpha} \prod_{n=0}^{\infty} \frac{s-t q^{n}}{s-t q^{n+\alpha}}
$$

We define the $q$-gamma function as following

$$
\Gamma_{q}(s)=(1-q)^{(s-1)}(1-q)^{1-s}, s \in \mathbb{R} \backslash\{0,-1,-2, \cdots\}
$$

and satisfies $\Gamma_{q}(s+1)=[s]_{q} \Gamma_{q}(s)$.
For $0<q<1$, the $q$-derivative of a function $f$ is defined by

$$
D_{q} f(s)=\frac{\mathrm{d}_{q}}{\mathrm{~d}_{q} s} f(s)=\frac{f(s)-f(q s)}{(1-q) s},\left(D_{q} f\right)(0)=\lim _{s \rightarrow 0}\left(D_{q} f\right)(s), s \neq 0
$$

The higher order $q$-derivatives are defined by

$$
D_{q}^{0} f(s)=f(s),\left(D_{q}^{n} f\right)(s)=D_{q}\left(D_{q}^{n-1} f\right)(s), n \in \mathbb{N}
$$

The $q$-integral of a function $f$ defined on the interval $[0, b]$ is given by

$$
I_{q} f(s)=\int_{0}^{s} f(t) \mathrm{d}_{q} t=s(1-q) \sum_{n=0}^{\infty} f\left(s q^{n}\right) q^{n}, s \in[0, b]
$$

provided that the series converges.
If $f$ is defined on the interval $[0, b]$ and $a \in[0, b]$, its $q$-integral from $a$ to $b$ is defined by

$$
\int_{a}^{b} f(s) \mathrm{d}_{q} s=\int_{0}^{b} f(s) \mathrm{d}_{q} s-\int_{0}^{a} f(s) \mathrm{d}_{q} s
$$

The higher order $q$-integrals are defined by

$$
I_{q}^{0} f(s)=f(s),\left(I_{q}^{n} f\right)(s)=I_{q}\left(I_{q}^{n-1} f\right)(s), n \in \mathbb{N}
$$

We note that $D_{q} I_{q} f(s)=f(s)$ and if $f$ is continuous at $s=0$, we get $I_{q} D_{q} f(s)=$ $f(s)-f(0)$.

To gain more details of the basic material on $q$-calculus, the readers can refer to $[1,2,6,7]$.

Definition 2.1. The fractional $q$-integral of the Riemann-Liouville of order $\alpha>0$ for a continuous function $f:[0,1] \rightarrow \mathbb{R}$ is given by

$$
I_{q}^{\alpha} f(t)=\frac{1}{\Gamma_{q}(\alpha)} \int_{0}^{t}(t-q s)^{(\alpha-1)} f(s) \mathrm{d}_{q} s, t \in[0,1]
$$

where $\Gamma_{q}(\alpha)=(1-q)^{(\alpha-1)}(1-q)^{1-\alpha}, 0<q<1$, and satisfies $\Gamma_{q}(\alpha+1)=[\alpha]_{q} \Gamma_{q}(\alpha)$.
Definition 2.2. The fractional $q$-derivative of the Riemann-Liouville of order $\alpha>0$ is given by $D_{q}^{0} f(t)=f(t)$ and

$$
D_{q}^{\alpha} f(t)=D_{q}^{n} I_{q}^{n-\alpha} f(t)
$$

where $n$ is the smallest integer greater than or equal to $\alpha$.
Lemma 2.1 (Theorem 2.0.5, [4]). Let $\alpha>0$ and $n$ be the smallest integer greater than or equal to $\alpha$. Then for $t \in[0,1]$, the following equality holds

$$
\left(I_{q}^{\alpha} D_{q}^{\alpha} f\right)(t)=f(t)+\sum_{k=0}^{n-1} \frac{t^{\alpha-n+k}}{\Gamma_{q}(\alpha+k-n+1)} D_{q}^{k} f(0)
$$

Lemma 2.2 (Lemma 2.5, [10]). Given $g(t) \in C[0,1]$, the unique solution of the following problem

$$
\begin{align*}
\left(D_{q}^{\alpha} x\right)(t)+g(t) & =0,0<t<1,2<\alpha<3  \tag{2.1}\\
x(0)=D_{q} x(0) & =D_{q} x(1)=0 \tag{2.2}
\end{align*}
$$

is

$$
x(t)=\int_{0}^{1} G(t, q s) g(s) d_{q} s
$$

where

$$
G(t, q s)=\frac{1}{\Gamma_{q}(\alpha)} \begin{cases}(1-q s)^{(\alpha-2)} t^{\alpha-1}-(t-q s)^{(\alpha-1)}, & 0 \leqslant q s \leqslant t \leqslant 1  \tag{2.3}\\ (1-q s)^{(\alpha-2)} t^{\alpha-1}, & 0 \leqslant t \leqslant q s \leqslant 1\end{cases}
$$

Here $G(t, q s)$ is called the Green's function of boundary value problem (2.1)-(2.2).
Lemma 2.3 (Lemma 2.6, [10]). Suppose $2<\alpha<3$, then the function $G(t, q s)$ defined by (2.3) satisfies the following inequalities:
(i) $G(t, q s) \geqslant 0, t, s \in[0,1]$.
(ii) $t^{\alpha-1} G(1, q s) \leqslant G(t, q s) \leqslant G(1, q s), t, s \in[0,1]$.

Definition 2.3. If $P$ is a cone of the real Banach space $E$, a mapping $\theta: P \rightarrow[0, \infty)$ is continuous and with

$$
\theta(t x+(1-t) y) \geqslant t \theta(x)+(1-t) \theta(y), \quad x, y \in P, t \in[0,1]
$$

is called a nonnegative concave continuous functional $\theta$ on $P$.
We will employ the following notations on positive constants $r, r_{1}, r_{2}$ for the later content.

$$
\begin{gathered}
P_{r}=\{x \in P:\|x\|<r\}, \\
\bar{P}_{r}=\{x \in P:\|x\| \leqslant r\},
\end{gathered}
$$

and

$$
P\left(\theta, r_{1}, r_{2}\right)=\left\{x \in P: \theta(x) \geqslant r_{1},\|x\| \leqslant r_{2}\right\}
$$

For the convenience, we show the Leggett-Williams fixed point theorem as follows.

Lemma 2.4 (P347 Theorem 5.4, [5]). Let $E=(E,\|\cdot\|)$ be a Banach space, $P \subset E$ be a cone of $E$, and $r_{3}>0$ be a constant. Suppose there exists a concave nonnegative continuous functional $\theta$ on $P$ with $\theta(x) \leqslant\|x\|$ for $x \in \bar{P}_{r_{3}}$. Let $T: \bar{P}_{r_{3}} \rightarrow \bar{P}_{r_{3}}$ be a completely continuous operator. Assume there are numbers $r, r_{1}$ and $r_{2}$ with $0<r<r_{1}<r_{2} \leq r_{3}$ such that
(i) The set $\left\{x \in P\left(\theta, r_{1}, r_{2}\right): \theta(x)>r_{1}\right\}$ is nonempty and $\theta(T x)>r_{1}$ for all $x \in P\left(\theta, r_{1}, r_{2}\right) ;$
(ii) $\|T x\|<r$ for $x \in \bar{P}_{r}$;
(iii) $\theta(T x)>r_{1}$ for all $x \in P\left(\theta, r_{1}, r_{3}\right)$ with $\|T x\|>r_{2}$.

Then $T$ has at least three fixed points $x_{1}, x_{2}$ and $x_{3} \in \bar{P}_{r_{3}}$. Furthermore we have $\max _{t \in[0,1]} x_{1}(t)<r, r_{1}<\min _{t \in[0,1]} x_{2}(t)<\max _{t \in[0,1]} x_{2}(t)<r_{3} \quad$ and $\quad r<\max _{t \in[0,1]} x_{3}(t) \leq r_{3}, \min _{t \in[0,1]} x_{3}(t)<r_{1}$.

## 3. Existence of three positive solutions

This section, we will obtain the main results of this paper by making use of the lemmas in Section 2. Let $C[0,1]$ be the space of all continuous real functions defined on $[0,1]$ with the maximum norm $\|x\|=\max _{t \in[0,1]}|x(t)|$. It is obviously a Banach space.
Define the cone $P \subset C[0,1]$ as following:

$$
P=\{x \in C[0,1]: x(t) \geqslant 0, t \in[0,1]\}
$$

From Lemma 2.2, we know that $x(t)$ is a solution of boundary value problem (1.1)-(1.2) if and only if it satisfy

$$
\begin{equation*}
x(t)=\int_{0}^{1} G(t, q s) f(s, x(s)) \mathrm{d}_{q} s, t \in[0,1] \tag{3.1}
\end{equation*}
$$

Then, the positive solutions $x(t)$ of problem (1.1)-(1.2) are the fixed points of $T$ in $C[0,1]$ that defined by

$$
\begin{equation*}
(T x)(t)=\int_{0}^{1} G(t, q s) f(s, x(s)) \mathrm{d}_{q} s, t \in[0,1] \tag{3.2}
\end{equation*}
$$

In line with Lemma 3.1 of [10], $T: P \rightarrow P$ is completely continuous.
Next, by using Lemma 2.4, we obtain sufficient conditions for the existence of three positive solutions to the problem (1.1)-(1.2). To acquire our results, we take a positive number $\nu \in(0,1)$, set the nonnegative concave continuous function $\theta$ on $P$ be defined by

$$
\begin{equation*}
\theta(x)=\min _{t \in[\nu, 1]} x(t) . \tag{3.3}
\end{equation*}
$$

Denote

$$
\begin{gathered}
f^{0}=\limsup _{x \rightarrow 0} \max _{t \in[0,1]} \frac{f(t, x)}{x}, \quad f^{\infty}=\limsup _{x \rightarrow+\infty} \max _{t \in[0,1]} \frac{f(t, x)}{x} \\
\rho^{-1}=\int_{0}^{1} G(1, q s) \mathrm{d}_{q} s, \quad \omega^{-1}=\int_{\nu}^{1} G(1, q s) \mathrm{d}_{q} s
\end{gathered}
$$

And suppose that the function $f(t, x)$ satisfies the following condition:
(H) $f(t, x)$ is a nonnegative continuous function on $[0,1] \times[0,+\infty)$ and there exists $t_{n} \rightarrow 0$ such that $f\left(t_{n}, x\left(t_{n}\right)\right)>0, n=1,2, \cdots$.

Theorem 3.1. Suppose the condition (H) holds and there exist constants $0<r<$ $r_{1}$ such that
(H1) $f(t, x)<\rho r$ for $(t, x) \in[0,1] \times[0, r]$;
(H2) $f(t, x) \geqslant \frac{\omega}{\nu^{\alpha-1}} r_{1}$ for $(t, x) \in[\nu, 1] \times\left[r_{1}, r_{3}\right]$, where $r_{3}>\frac{r_{1}}{\nu^{\alpha-1}}$;
(H3) $f(t, x) \leqslant \kappa x+\beta$ for $(t, x) \in[0,1] \times[0,+\infty)$, where $\kappa, \beta$ are positive numbers.
Then the boundary value problem (1.1)-(1.2) has at least three positive solutions $x_{1}, x_{2}$ and $x_{3}$.

Proof. Set $r_{3}>\max \left\{\frac{\beta}{\rho-\kappa}, \frac{r_{1}}{\nu^{\alpha-1}}\right\}$, then for $x \in \bar{P}_{r_{3}}$, we have from (3.2) and (H3)

$$
\begin{aligned}
\|T x\| & =\max _{t \in[0,1]} \int_{0}^{1} G(t, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& \leqslant \int_{0}^{1} G(1, q s)(\kappa x(s)+\beta) \mathrm{d}_{q} s \\
& \leqslant(\kappa\|x\|+\beta) \int_{0}^{1} G(1, q s) \mathrm{d}_{q} s \\
& =\frac{(\kappa\|x\|+\beta)}{\rho} \\
& <r_{3}
\end{aligned}
$$

i.e, $T x \in P_{r_{3}}$. Therefore $T: \bar{P}_{r_{3}} \rightarrow \bar{P}_{r_{3}}$ be a completely continuous operator. By (H1), we can get

$$
\begin{aligned}
\|T x\| & \leqslant \int_{0}^{1} G(1, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& <\rho r \int_{0}^{1} G(1, q s) \mathrm{d}_{q} s \\
& =r
\end{aligned}
$$

Hence assumption (ii) of Lemma 2.4 is satisfied.
We choose $x_{0}=\frac{\left(\nu^{\alpha-1}+1\right) r_{1}}{2 \nu^{\alpha-1}}$ for $t \in[\nu, 1]$, then $x_{0} \in\left\{x \in P\left(\theta, r_{1}, \frac{1}{\nu^{\alpha-1}} r_{1}\right)\right.$ : $\left.\theta(x)>r_{1}\right\}$, which implies $\left\{x \in P\left(\theta, r_{1}, \frac{1}{\nu^{\alpha-1}} r_{1}\right): \theta(x)>r_{1}\right\}$ is nonempty set. If $x \in P\left(\theta, r_{1}, \frac{1}{\nu^{\alpha-1}} r_{1}\right)$, then $r_{1} \leqslant x(t) \leqslant \frac{1}{\nu^{\alpha-1}} r_{1}$ for $\nu \leqslant t \leqslant 1$. Thus

$$
\begin{aligned}
\theta(T x) & =\min _{\nu \leqslant t \leqslant 1} \int_{0}^{1} G(t, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& >\int_{\nu}^{1} \min _{\nu \leqslant t \leqslant 1} G(t, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& >\int_{\nu}^{1} \nu^{\alpha-1} G(1, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& \geqslant \frac{\omega}{\nu^{\alpha-1}} r_{1} \int_{\nu}^{1} \nu^{\alpha-1} G(1, q s) \mathrm{d}_{q} s \\
& =r_{1}
\end{aligned}
$$

From the above inequality, we see that $\theta(T x)>r_{1}$ for all $x \in P\left(\theta, r_{1}, \frac{1}{\nu^{\alpha-1}} r_{1}\right)$. This shows that condition (i) of Lemma 2.4 is satisfied.

Finally, for $x \in P\left(\theta, r_{1}, r_{3}\right)$ with $\|T x\|>\frac{1}{\nu^{\alpha-1}} r_{1}$, we get

$$
\begin{aligned}
\theta(T x) & =\min _{\nu \leqslant t \leqslant 1} \int_{0}^{1} G(t, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& \geqslant \int_{0}^{1} \min _{\nu \leqslant t \leqslant 1} t^{\alpha-1} G(1, q s) f(s, x(s)) \mathrm{d}_{q} s
\end{aligned}
$$

$$
\begin{aligned}
& \geqslant \nu^{\alpha-1} \int_{0}^{1} G(1, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& \geqslant \nu^{\alpha-1} \int_{0}^{1} \max _{0 \leqslant t \leqslant 1} G(t, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& >r_{1} .
\end{aligned}
$$

This confirms that condition (iii) of Lemma 2.4 is fulfilled. By virtue of Lemma 2.4, the boundary value problem (1.1)-(1.2) has at least three solutions $x_{1}, x_{2}$ and $x_{3}$. Take into account that condition (H) holds, we have $x_{i}(t)>0,0<t<1, i=1,2,3$. The proof is completed.

Theorem 3.2. Assume the condition (H) holds. There exist constants $0<r<$ $r_{1}<r_{3}\left(r_{3}>\frac{r_{1}}{\nu^{\alpha-1}}\right)$ such that (H1),(H2) and (H4) are satisfied, where
(H4) $f(t, x) \leqslant \rho r_{3}$ for $(t, x) \in[0,1] \times\left[0, r_{3}\right]$.
Then the boundary value problem (1.1)-(1.2) has at least three positive solutions $x_{1}, x_{2}$ and $x_{3}$ such that

$$
\begin{array}{ll} 
& \max _{t \in[0,1]} x_{1}(t)<r, r_{1}<\min _{t \in[\nu, 1]} x_{2}(t)<\max _{t \in[0,1]} x_{2}(t)<r_{3} \\
\text { and } & r<\max _{t \in[0,1]} x_{3}(t) \leqslant r_{3}, \min _{t \in[\nu, 1]} x_{3}(t)<r_{1} .
\end{array}
$$

Proof. From (H4), we get

$$
\begin{aligned}
\|T x\| & =\max _{t \in[0,1]} \int_{0}^{1} G(t, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& \leqslant \int_{0}^{1} G(1, q s) f(s, x(s)) \mathrm{d}_{q} s \\
& <\rho r_{3} \int_{0}^{1} G(1, q s) \mathrm{d}_{q} s \\
& =r_{3} .
\end{aligned}
$$

Therefore $T: \bar{P}_{r_{3}} \rightarrow \bar{P}_{r_{3}}$. The remainder of proof is similar to the proof of Theorem 3.1 and is therefore omitted. By Lemma 2.4, the boundary value problem (1.1)-(1.2) has at least three positive solutions $x_{1}, x_{2}$ and $x_{3}$ satisfying

$$
\begin{array}{ll} 
& \max _{t \in[0,1]} x_{1}(t)<r, r_{1}<\min _{t \in[\nu, 1]} x_{2}(t)<\max _{t \in[0,1]} x_{2}(t)<r_{3} \\
\text { and } & r<\max _{t \in[0,1]} x_{3}(t) \leqslant r_{3}, \min _{t \in[\nu, 1]} x_{3}(t)<r_{1} .
\end{array}
$$

The proof is complete.
Theorem 3.3. Assume the condition (H) holds. There exist constants $0<r<r_{1}$ such that (H1), (H2) are satisfied, and function $f(t, x)$ satisfies
(H5) $f^{\infty}<\rho$.
Then the boundary vale problem (1.1)-(1.2) has at least three positive solutions.

Proof. From the assumption (H5), there exist $0<\sigma<\rho$ and $R>0$, when $x \geqslant R$, we have

$$
f(t, x) \leqslant \sigma x
$$

Set $M=\max _{(t, x) \in[0,1] \times[0, R]} f(t, x)$, consequently

$$
0 \leqslant f(t, x) \leqslant \sigma x+M, 0 \leqslant x<+\infty
$$

This shows that condition (H3) of Theorem 3.1 is satisfied. By Theorem 3.1, the boundary value problems (1.1)-(1.2) has at least three positive solutions. The proof is completed.
Theorem 3.4. Assume there exist two positive constants $r_{1}, r_{3}\left(r_{3}>\frac{1}{\nu^{\alpha-1}} r_{1}\right)$ such that the condition (H), (H2) and (H4) hold. And function $f(t, x)$ satisfies
(H6) $f^{0}<\rho$.
Then the boundary vale problems (1.1)-(1.2) has at least three positive solutions.
Proof. In line with (H6), it is easy to see that there exists a positive constant $r<r_{1}$ such that for $\|x\|<r$, we have

$$
f(t, x(t))<\rho x
$$

Namely,

$$
f(t, x(t))<\rho r,\|x\|<r
$$

This implies that conditions of Theorem 3.2 is satisfied. By Theorem 3.2, the boundary vale problem (1.1) has at least three positive solutions. The proof is completed.

In the light of the proof of Theorem 3.3 and Theorem 3.4, we obtain one theorem and four corollaries as follows.
Theorem 3.5. Assume the function $f(t, x)$ satisfies conditions (H), (H2), (H5) and (H6). Then the boundary vale problem (1.1)-(1.2) has at least three positive solutions.

Corollary 3.1. Assume the conditions (H),(H2) and (H3) hold. The function $f(t, x)$ satisfies $f^{0}=0$. Then the boundary vale problem (1.1)-(1.2) has at least three positive solutions.

Corollary 3.2. Assume the conditions (H), (H1) and (H2) hold. The function $f(t, x)$ satisfies $f^{\infty}=0$. Then the boundary vale problem (1.1)-(1.2) has at least three positive solutions.

Corollary 3.3. Assume the conditions (H),(H2) and (H4) hold. The function $f(t, x)$ satisfies $f^{\infty}=0$. Then the boundary vale problem (1.1)-(1.2) has at least three positive solutions.
Corollary 3.4. Assume the conditions (H) and (H2) hold. The function $f(t, x)$ satisfies $f^{0}=0$ and $f^{\infty}=0$. Then the boundary vale problem (1.1)-(1.2) has at least three positive solutions.

## 4. Examples

This section, we present three examples to illustrate our results. We take $\alpha=$ $\frac{5}{2}, q=\frac{1}{2}, \nu=\frac{1}{4}$, by estimating, we then have $\rho>7.8, \omega<3.0015$.
Example 4.1. We take

$$
f(t, x)=\left\{\begin{aligned}
0.26 t+25 x^{2}, & (t, x) \in[0,1] \times[0,1] \\
0.26 t+24+x, & (t, x) \in[0,1] \times(1,+\infty)
\end{aligned}\right.
$$

There exist constants $r=0.04$ and $r_{1}=1.03$ such that

$$
\begin{aligned}
& f(t, x)=0.26 t+25 x^{2}<7.8 \times 0.04<\rho r \text { for }(t, x) \in[0,1] \times[0, r] \\
& f(t, x)=0.26 t+24+x>3.0015 \cdot \frac{1}{\nu^{\alpha-1}} r>\frac{\omega}{\nu^{\alpha-1}} r_{1} \text { for }(t, x) \in[\nu, 1] \times\left[r_{1}, \frac{r_{1}}{\nu^{\alpha-1}}+\right. \\
& f(t, x) \leqslant 0.26+25 x \text { for }(t, x) \in[0,1] \times(0,+\infty)
\end{aligned}
$$

$1]$.
All the conditions of Theorem 3.1 hold. Thus, this moment, by virtue of Theorem 3.1 we know that the boundary value problem (1.1)-(1.2) has three positive solutions.

Example 4.2. We take

$$
f(t, x)=\left\{\begin{array}{cr}
52.5 x^{3} \cdot 2^{-t}, & (t, x) \in[0,1] \times[0,1] \\
2^{-t}\left[45 x^{\frac{1}{2}}+7.5 x\right], & (t, x) \in[0,1] \times(1,+\infty)
\end{array}\right.
$$

There exist constants $r=0.36$ and $r_{1}=1.15$ such that

$$
\begin{aligned}
& f^{\infty}=7.5<\rho \text { for }(t, x) \in[0,1] \times[0,+\infty) \\
& f(t, x) \geqslant 3.0015 \cdot \frac{r_{1}}{\nu^{\alpha-1}}>\frac{\omega}{\nu^{\alpha-1}} r_{1} \text { for }(t, x) \in[\nu, 1] \times\left[r_{1}, \frac{r_{1}}{\nu^{\alpha-1}}+1\right] . \\
& f(t, x) \leqslant 52.5 r^{3}<\rho r \text { for }(t, x) \in[0,1] \times[0, r]
\end{aligned}
$$

All the conditions of Theorem 3.3 hold. Hence, under these circumstances we know that the boundary value problem (1.1)-(1.2) has three positive solutions, by using Theorem 3.3.

Example 4.3. We seek

$$
f(t, x)=\left\{\begin{array}{lr}
6 x+36 x^{4}, & (t, x) \in[0,1] \times[0,1] \\
35 x^{\frac{1}{2}}+7 x, & (t, x) \in[0,1] \times(1,+\infty)
\end{array}\right.
$$

There exist constant $r_{1}=3$ such that

$$
\begin{aligned}
& f^{\infty}=7<7.8<\rho \\
& f^{0}=6<7.8<\rho \\
& f(t, x)=35 x^{\frac{1}{2}}+7 x>\frac{\omega}{\nu^{\alpha-1}} r_{1} \text { for }(t, x) \in[\nu, 1] \times\left[r_{1}, \frac{r_{1}}{\nu^{\alpha-1}}+1\right]
\end{aligned}
$$

All the conditions of Theorem 3.5 hold. Thus, in this case, by using Theorem 3.5 we know that the boundary value problem (1.1)-(1.2) has three positive solutions.

## Competing interests

The authors declare that they have no competing interests.

## Acknowledgements

The authors are very grateful to the reviewers for their valuable suggestions and useful comments, which led to an improvement of this paper.

## References

[1] R. Agarwal, Certain fractional q-integrals and $q$-derivatives, Proc. Camb. Philos. Soc., 1996, 66, 365-370.
[2] W. Al-Salam, Some fractional $q$-integrals and $q$-derivatives, Proc. Edinb. Math. Soc., 1966/1967, 15(2), 135-140.
[3] A. Alsaedi, B. Ahmad and H. Al-Hutami, A study of nonlinear fractional $q$ difference equations with nonlocal integral boundary conditions, Abstr. Appl. Anal., 2013, Art. ID 410505.
[4] R. Ferreira, Positive solutions for a class of boundary value problems with fractional $q$-differences, Comput. Math. Appl., 2011, 61, 367-373.
[5] D. J. Guo, Nonlinear Functional Analysis, second ed., Shandong Sci. Tec. Press, Jinan, 2001.
[6] F. Jackson, On q-functions and a certain difference operator, Trans. R. Soc. Edinb., 1908, 46, 253-281.
[7] F. Jackson, On q-definite integrals, Q. J. Pure Appl. Math., 1910, 41, 193-203.
[8] Ilknur Koca, Amethod for solving differential equations of $q$-fractional order, Appl. Math. Comput., 2015, 266, 1-5.
[9] Y. F. Li and W. G. Yang, Monotone iterative method for nonlinear fractional $q$ difference equations with integral boundary conditions, Adv. Differ. Equ., 2015, 2015, 294.
[10] X. H. Li, Z. L. Han and S. R. Sun, Existence of positive solutions of nonlinear fractional $q$-difference equation with parameter, Adv. Differ. Equ., 2013, 2013, 260.
[11] X. H. Li, Z. L. Han, S. R. Sun and L. Y. Sun, Eigenvalue problems of fractional $q$-difference equations with generalized p-Laplacian, Appl. Math. Lett., 2016, 57, 46-53.
[12] J. Ren and C. B. Zhai, A fractional q-difference equation with integral boundary conditions and comparison theorem, Int. J. Nonlinear Sci. Numerical. Simul., 2017, 18(7-8), 575-583.
[13] G. T. Wang, W. Sudsutad, L. Zhang and J. Tariboon, Monotone iterative technique for a nonlinear fractional $q$-difference equation of Caputo type, Adv. Differ. Equ., 2016, 2016, 211.
[14] W. G. Yang, Positive solutions for nonlinear semipositone fractional $q$ difference system with coupled integral boundary conditions, Appl. Math. Comput., 2014, 244, 702-725.
[15] C. B. Zhai and J. Ren, Positive and negative solutions of a boundary value problem for a fractional $q$-difference equation, Adv. Differ. Equ., 2017, 2017, 82.
[16] C. B. Zhai and J. Ren, The unique solution for a fractional $q$-difference equation with three-point boundary conditions, Indag. Math., 2018, 29(3), 948-961.
[17] S. Zhang, Positive solutions for boundary-value problems of nonlinear fractional differential equations, Electron J. Differ. Equat., 2016, 36, 1-12.
[18] Y. L. Zhao, H. B. Chen and Q. M. Zhang, Existence results for fractional $q$ difference equations with nonlocal q-integral boundary conditions, Adv. Differ. Equ., 2013, 2013, 48.
[19] Y. G. Zhao, S. R. Sun, Z. L. Han and Q. P. Li, The existence of multiple postive solutions for boundary value problems of nonlinear fractional differential equations, Commun. Nonlinear Sci. Numer. Simul., 2011, 16, 2086-2097.
[20] W. X. Zhou and H. Z. Liu, Existence solutions for boundary value problem of nonlinear fractional q-difference equations, Adv. Differ. Equ., 2013, 2013, 113.


[^0]:    ${ }^{\dagger}$ the corresponding author. Email address:dtkangshugui@126.com(S. Kang)
    ${ }^{1}$ School of Mathematics and Statistics, Shanxi Datong University, Xingyun Street, 037009, China
    ${ }^{2}$ School of Mathematical Sciences and LPMC, Nankai University, Tianjin, 300071, China
    *The authors were supported by National Natural Science Foundation of China (Grant No.11871314), Shanxi Datong Scientific Research Project(2018146), Scientific Research Project of Shanxi Datong University(2016K9, 2017K4) and 131 Talent Project at Shanxi Province.

